

# Quasilinear Hyperbolic Systems, Nonlinear Superposition and Solitons

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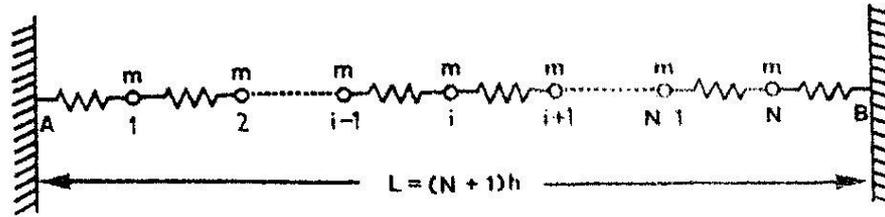


Fig.1. A one-dimensional nonlinear lattice

$$\frac{\partial^2 y}{\partial t^2} = c^2 \left[ 1 + \alpha(1 + p)h^p \left( \frac{\partial y}{\partial x} \right)^p \right] \frac{\partial^2 y}{\partial x^2},$$

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \mu \frac{\partial^3 u}{\partial x^3} = 0,$$

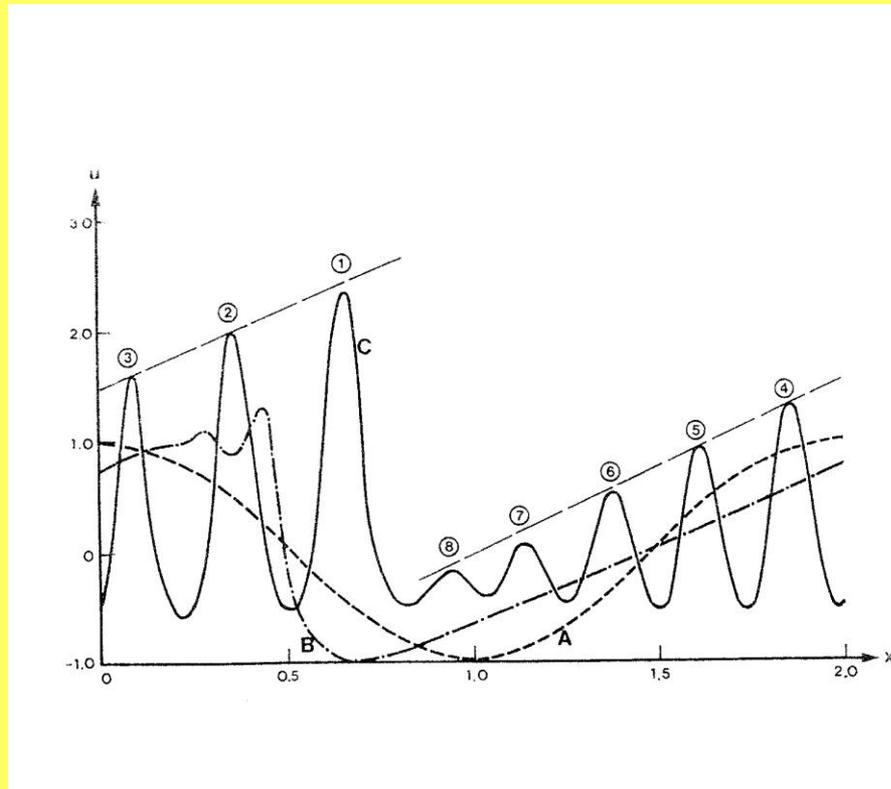


Fig.2 The asymptotic evolution of a train of solitons from an initial sinusoid

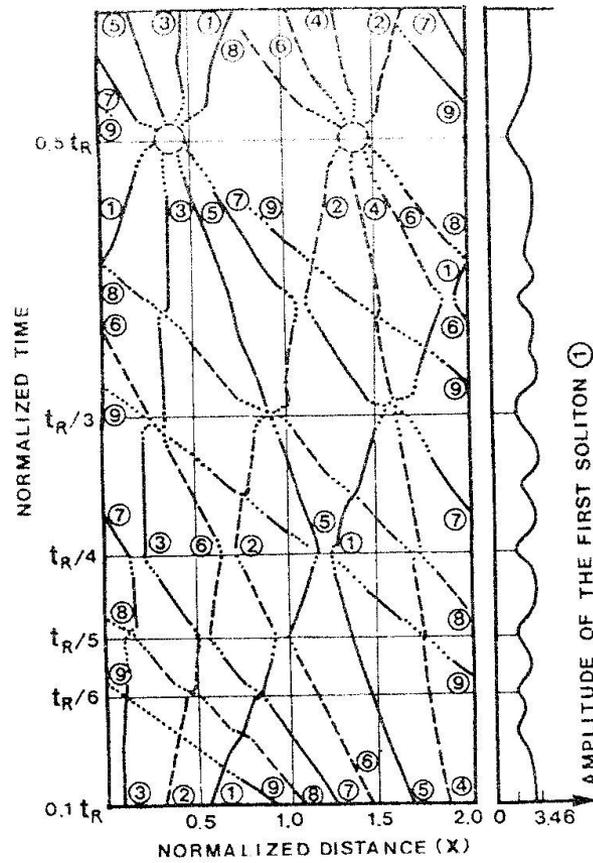


Fig.3. Paths of interacting solitons computed by Zabusky and Kruskal

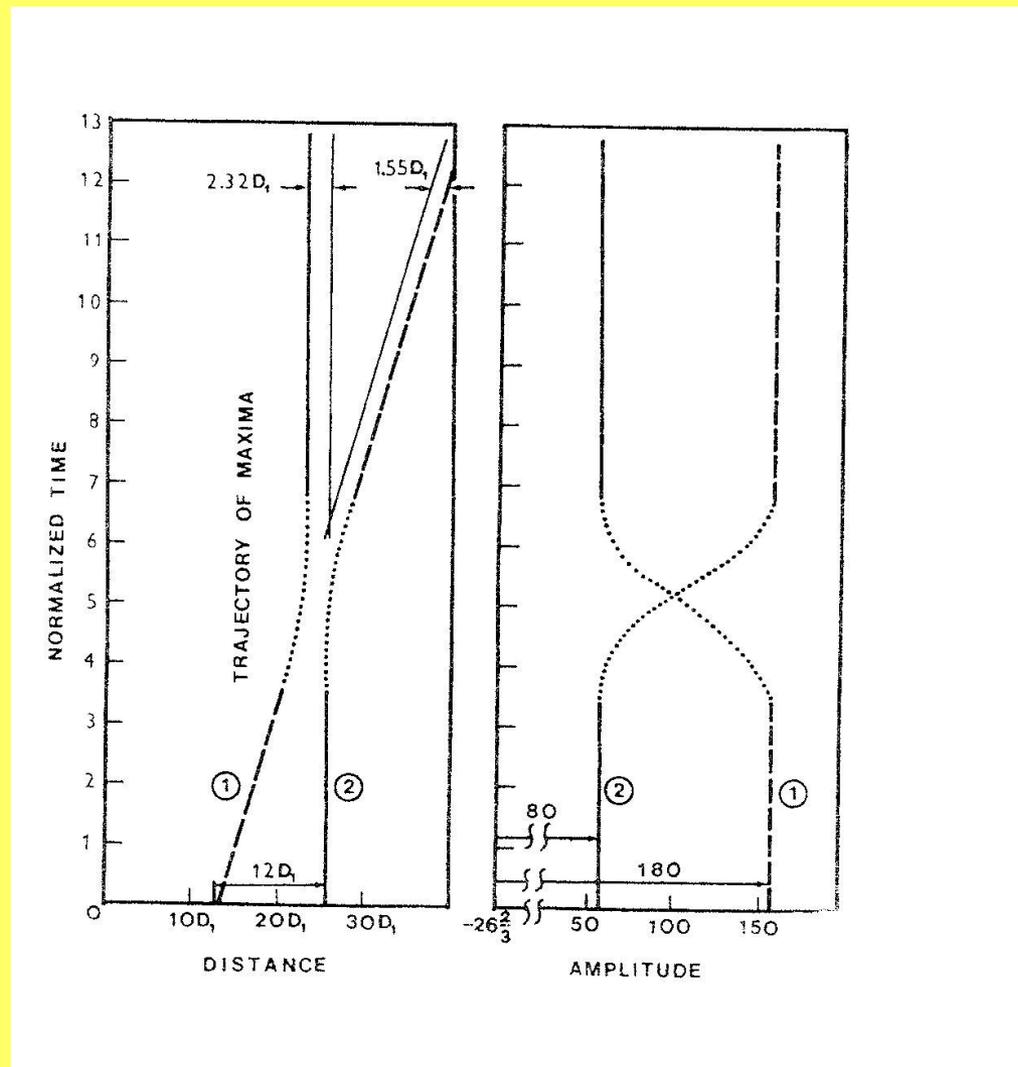


Fig.4 The preservation of soliton shape after soliton interaction

# The Development of Discontinuous Solutions

A natural starting point for this brief review of discontinuous solutions is the Burgers equation

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \mu \frac{\partial^2 u}{\partial x^2}, \quad (\mu > 0)$$

$$\frac{\partial u}{\partial t} + \frac{1}{2} (u^2)_x = 0.$$

## A Weak Solution of Burgers Equation

Let  $u_\mu$  be a solution of Burgers equation, then

$$(u_\mu)_t + u_\mu(u_\mu)_x + \mu(u_\mu)_{xx} = 0 \quad (\mu < 0).$$

With  $\varphi$  a  $C^1$  test function with compact support, multiply

Burgers equation by  $\varphi$  and integrate over the half-plane  $t > 0$

to switch the derivatives from  $u$  to  $\varphi$ , giving

$$\iint (\varphi_t u_\mu + \frac{1}{2} \varphi_x u_\mu^2 + \mu \varphi_{xx} u_\mu) dx dt = 0.$$

As  $\mu \rightarrow 0$  this implies that

$$\iint (\varphi_t u_\mu + \frac{1}{2} u_\mu^2) dx dt = 0.$$

This is the condition that Burgers equation is satisfied by  $u_\mu$

in the weak sense. Classical solutions are a special case of

weak solutions, and both satisfy the Rankine-Hugoniot

jump condition.

$$u_t + f(u)_x \equiv u_t + f'(u)u_x = 0 \quad (\text{first conservation law})$$

$$v(u)_t + f'(u)v(u)_x = 0 \quad (\text{second conservation law})$$

$$v(u)_t + F(u)_x = 0 \quad \text{where} \quad F'(u) = f'(u)v(u)_x$$

Jump condition for first conservation law is

$$s_1 = [f(u_+) - f(u_-)] / (u_+ - u_-)$$

Jump condition for second conservation law is

$$s_2 = [F(u_+) - F(u_-)] / [v(u_+) - v(u_-)], \quad \text{so} \quad s_1 \neq s_2.$$

## Layered Solutions

$$u_t + f_x(u) = 0, \quad u(x, 0) = U(x)$$

$$|U| \leq U_0, \quad |U'| \leq U_1$$

$$f_1 = \max_{|s| \leq U_0} |f'(s)|, \quad f_2 = \max_{|s| \leq U_0} |f''(s)|, \quad |u| \leq U_0$$

**Time interval to be used**

$$h = 1/(2f_2U_1)$$

- i. Introduce a special smoothing operation for data on a line  $t = \text{constant}$ , denoted by  $S\{.\}$ .
- ii. Using the smoothed initial data  $S\{U\} = u_0(x, t)$ , find a strict solution  $u_1(x, t)$  in the layer  $0 \leq t \leq h$ .
- iii. In a second layer  $h \leq t \leq 2h$ , find a strict solution  $u_2(x, t)$  subject to smoothed initial data such  $u_2(x, h) = S\{u_1(x, h)\}$ .
- iv. Continue this layering process to obtain a sectionally continuous smoothed layered approximation for  $t > 0$

such that

$$u(x, t) = \begin{cases} u_1(x, t) & \text{for } 0 \leq t < h, \\ u_2(x, t) & \text{for } h \leq t < 2h, \\ u_3(x, t) & \text{for } 2h \leq t < 3h, \\ \vdots & \end{cases}.$$

- v. Then for a suitable smoothing operation, it can be proved that this layered approximate solution converges to a **unique weak solution** of (11) subject to the initial condition

$$u(x, 0) = U(x).$$

The smoothing process contains two steps. The first involves converting a bounded and continuous solution  $v(x)$  into a sequence of step function  $R_\varepsilon\{v(x)\}$

that together form a sequence of Riemann problems. This is achieved by defining

$$R_\varepsilon\{v(x)\} = \frac{1}{2\varepsilon} \int_{(i-2)\varepsilon}^{i\varepsilon} v(\xi) d\xi \quad \text{for} \quad (i-2)\varepsilon \leq x < i\varepsilon,$$

$$Av_\varepsilon\{R_\varepsilon\{v(x)\}\} = \frac{1}{2} \int_{-1}^1 R_\varepsilon\{v(x + \varepsilon\tau)\} d\tau.$$

$$\frac{f(u_+) - f(u_-)}{u_+ - u_-} \leq \frac{f(u_0) - f(u_-)}{u_0 - u_-},$$

# Nonlinear Superposition and the Riccati Equation.

$$y' + Qy + Ry^2 = P$$

The change of variable  $y = u'/Ru$  gives

$$Ru'' - (R' - QR)u' - PR^2u = 0.$$

$$C = \frac{(y_1 - y_3)(y_2 - y_4)}{(y_1 - y_4)(y_2 - y_3)}$$

# The Burgers Equation – a Dissipative Equation.

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = \mu \frac{\partial^2 u}{\partial x^2}, \quad (\mu > 0)$$

with  $u(x, 0) = U(x)$

Do solutions  $u_\mu(x, t)$  approach a limit as  $\mu \rightarrow 0$ , and if so does the limit satisfy the limiting differential equation, namely,

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = 0$$

$$u_t + \left( \frac{1}{2} u^2 - \mu u_x \right)_x = 0,$$

which may be considered to be a compatibility condition for the existence of a function  $\psi$  with the properties that

$$u = \psi_x \quad \text{and} \quad \mu u_x - \frac{1}{2} u^2 = \psi_t.$$

The substitution for  $u$  in the second equation then leads to the result

$$\mu \psi_{xx} - \frac{1}{2} \psi_x^2 = \psi_t.$$

Next, the introduction of what is now called the Hopf-Cole transformation  $\psi = -2\mu \ln \theta$  shows that

$$u = \psi_x = -2\mu \frac{\theta_x}{\theta},$$

after which the Burger's Equation is transformed into the linear heat equation.

$$\frac{\partial \theta}{\partial t} = \frac{\partial^2 \theta}{\partial x^2}.$$

We mention in passing that the Burgers equation describes the steady traveling wave solution called the **Burgers shock wave**

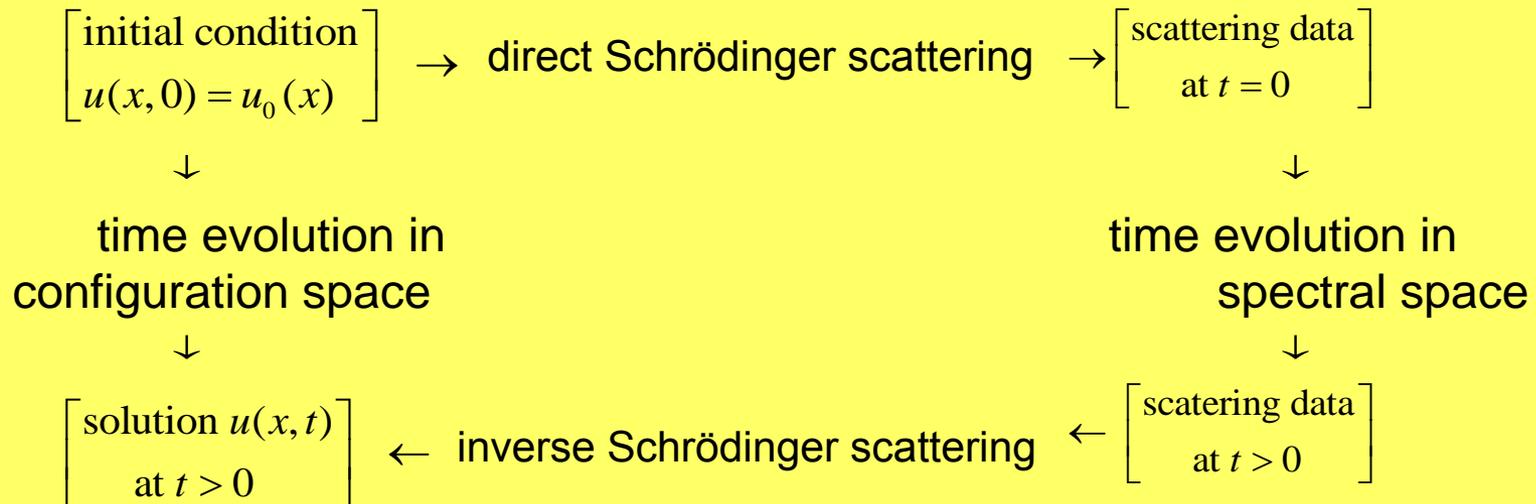
$$u(\zeta) = \frac{1}{2} \left( u_{\infty}^{-} + u_{\infty}^{+} \right) - \frac{1}{2} \left( u_{\infty}^{-} - u_{\infty}^{+} \right) \tanh \left[ \left( u_{\infty}^{-} - u_{\infty}^{+} \right) \zeta / (4\mu) \right],$$

with  $\zeta = x - ct$  and  $c = \frac{1}{2} \left( u_{\infty}^{-} + u_{\infty}^{+} \right)$ ,  $u_{\infty}^{-} > u_{\infty}^{+}$

# The KdV Equation – A Nonlinear Dispersive Equation.

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + \mu \frac{\partial^3 u}{\partial x^3} = 0,$$

The IST approach can be represented diagrammatically as follows:



The soliton property is not confined to the KdV equation and, for example, it applies to the equation

$$y_{xt} + \operatorname{sign}\left(\frac{dx}{ds}\right) \left[ \frac{y_{xx}}{\left(1 + y_x^2\right)^{3/2}} \right]_{xx} = 0$$

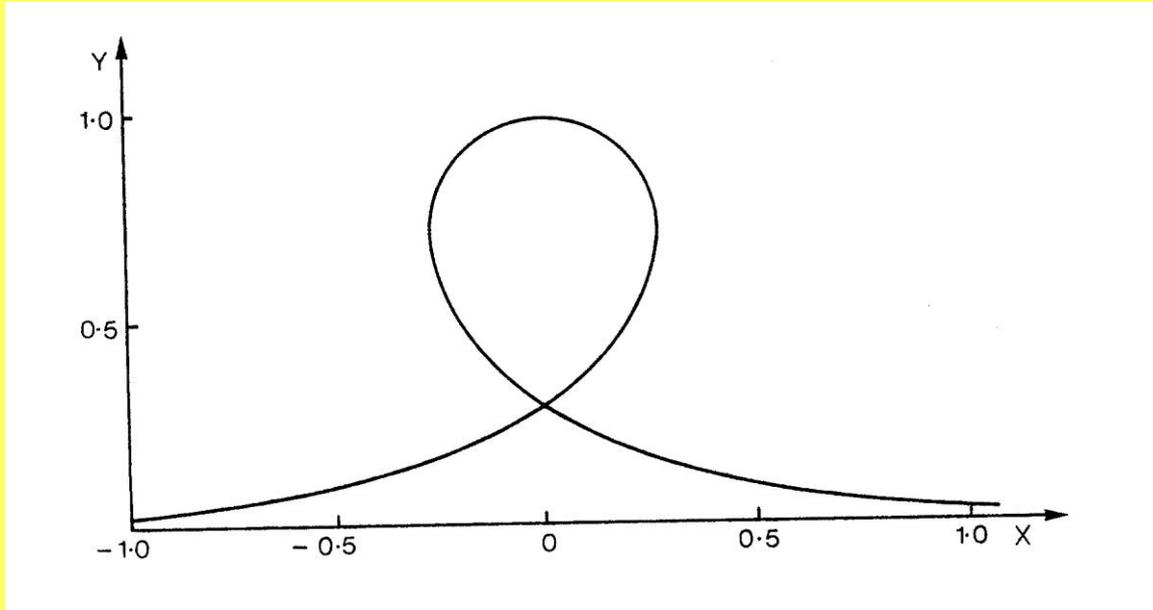


Fig.5 A single loop soliton

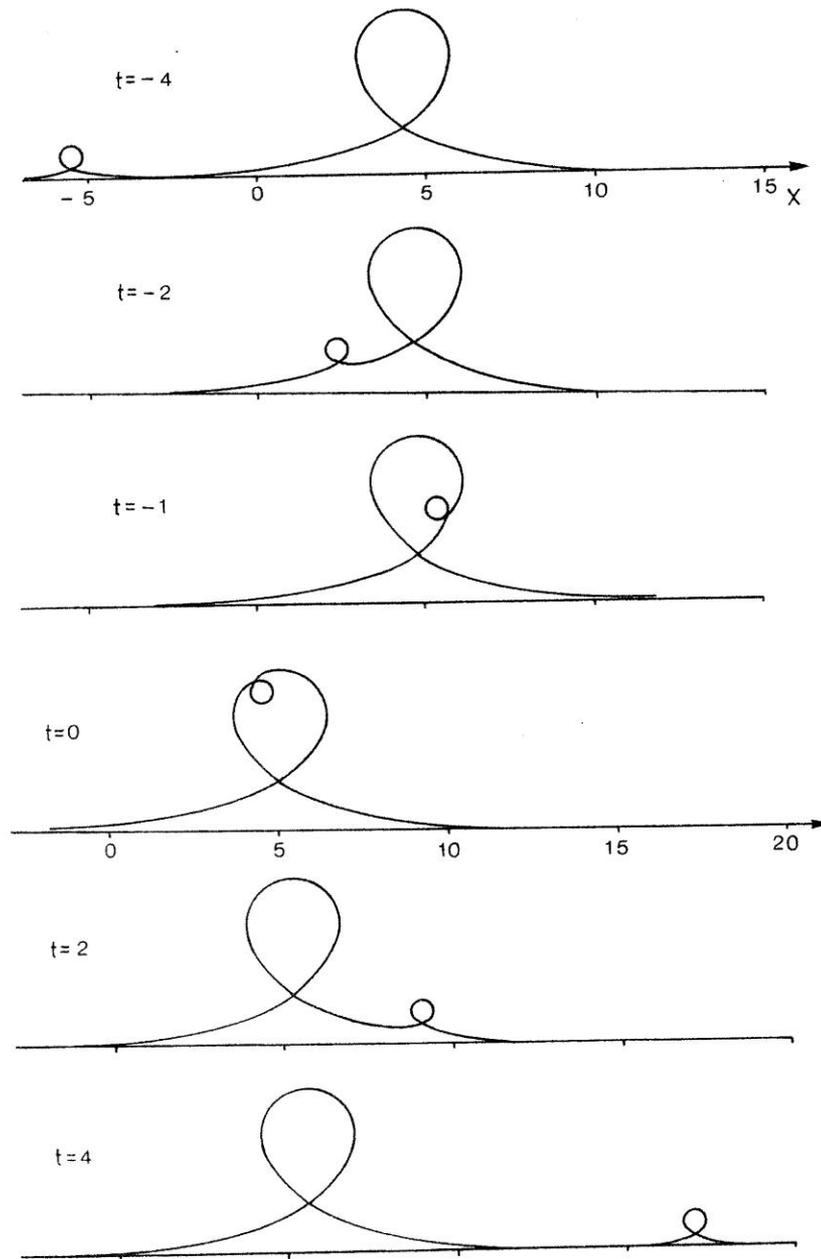


Fig.6. The interaction of two loop solitons

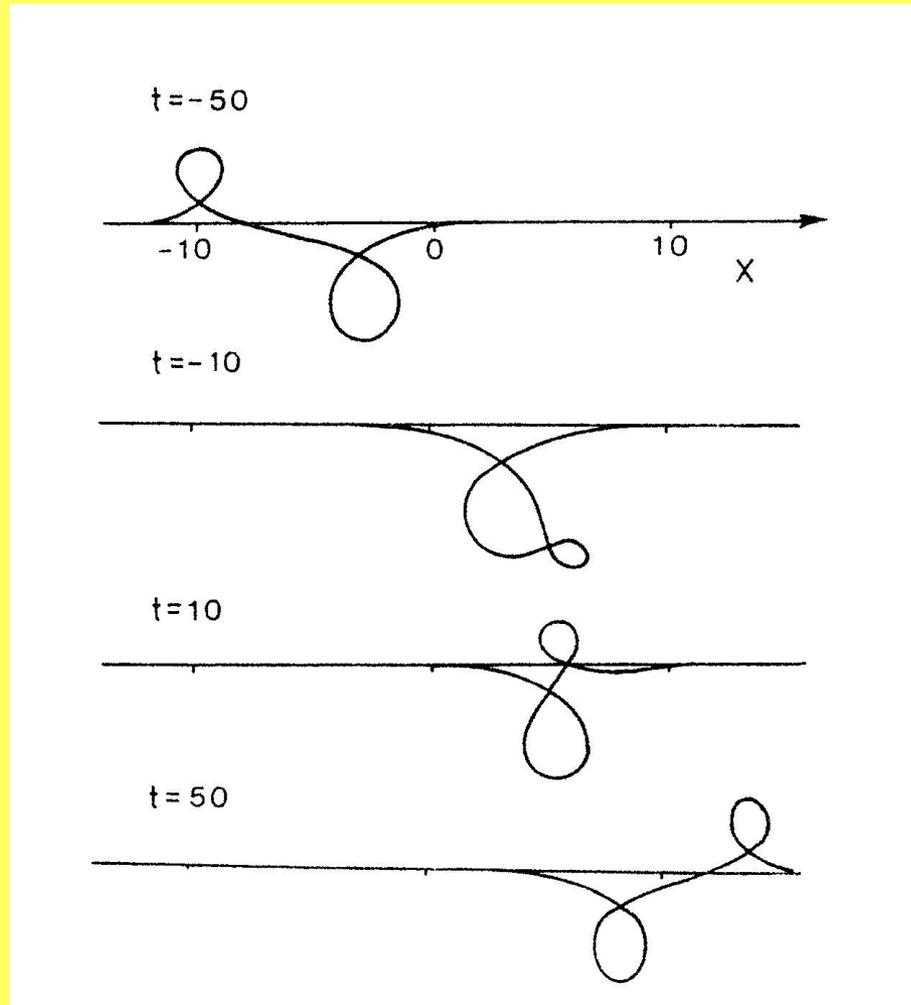


Fig.7. The interaction of a loop soliton and an anti-loop soliton

# Backlund Transformations

In brief, a Bäcklund transformation for a second-order equation for a dependent variable  $\varphi(\xi, \eta)$  is best described as the pair of relationships

$$\frac{\partial \varphi'}{\partial \xi} = P(\varphi', \varphi, \varphi_\xi, \varphi_\eta, \xi, \eta) \quad \text{and} \quad \frac{\partial \varphi'}{\partial \eta} = Q(\varphi', \varphi, \varphi_\xi, \varphi_\eta, \xi, \eta)$$

where the consistency condition for these two equations provides a new equation for  $\varphi'$ .

If it is possible to find such transformations that map into themselves, then any known solution  $\varphi$  may be used to find a new solution  $\varphi'$ .

One of the simplest examples of a Bäcklund transformation, though not related to wave propagation, is provided by the Cauchy-Riemann equations

$$\left. \begin{array}{l} \text{Laplace equation} \\ u_{xx} + u_{yy} = 0 \\ \text{Harmonic conjugate} \\ v_{xx} + v_{yy} = 0 \end{array} \right\} \Leftrightarrow \left\{ \begin{array}{l} \text{Bäcklund transformation} \\ \text{Cauchy-Riemann equations} \\ u_x = v_y \\ u_y = -v_x \end{array} \right.$$

Notice that in this rather special case the conjugate PDE for  $v$  happens to be the same as the original PDE for  $u$ , namely the Laplace equation.

# Linearity and Nonlinear Superposition.

$$\frac{\partial u}{\partial x} + a(x, y) \frac{\partial u}{\partial y} + b(x, y) f(u) = 0.$$

Now let us seek a superposition law  $g$ , such that  $u = g(v, w)$ ,

$$\begin{aligned} & \frac{\partial g}{\partial v} \left[ \frac{\partial v}{\partial x} + a(x, y) \frac{\partial v}{\partial y} + b(x, y) f(v) \right] + \frac{\partial g}{\partial w} \left[ \frac{\partial w}{\partial x} + a(x, y) \frac{\partial w}{\partial y} + b(x, y) f(w) \right] \\ & + b(x, y) \left[ f(g) - f(v) \frac{\partial g}{\partial v} - \frac{\partial f}{\partial w} \frac{\partial g}{\partial w} \right] = 0. \end{aligned}$$

However, as  $v$  and  $w$  are solutions of the equation, it will be satisfied if

$$f(v) \frac{\partial g}{\partial v} + f(w) \frac{\partial g}{\partial w} = f(g).$$

The general solution of this equation is

$$\int \frac{dg}{f(g)} = \int \frac{dv}{f(v)} + K \left[ \int \frac{dv}{f(v)} - \int \frac{dw}{f(w)} \right],$$

Now consider the special case  $f(u) = u$ , when

$$g(v, w) = wK(v/w).$$

The semilinear equation (41) then reduces to a **linear equation**, and the usual linear superposition becomes possible if

$$K(v/w) = A(v/w) + B,$$

where  $A$  and  $B$  are constants

$$u = g(v, w) = Av + Bw.$$

# Asymptotic Methods

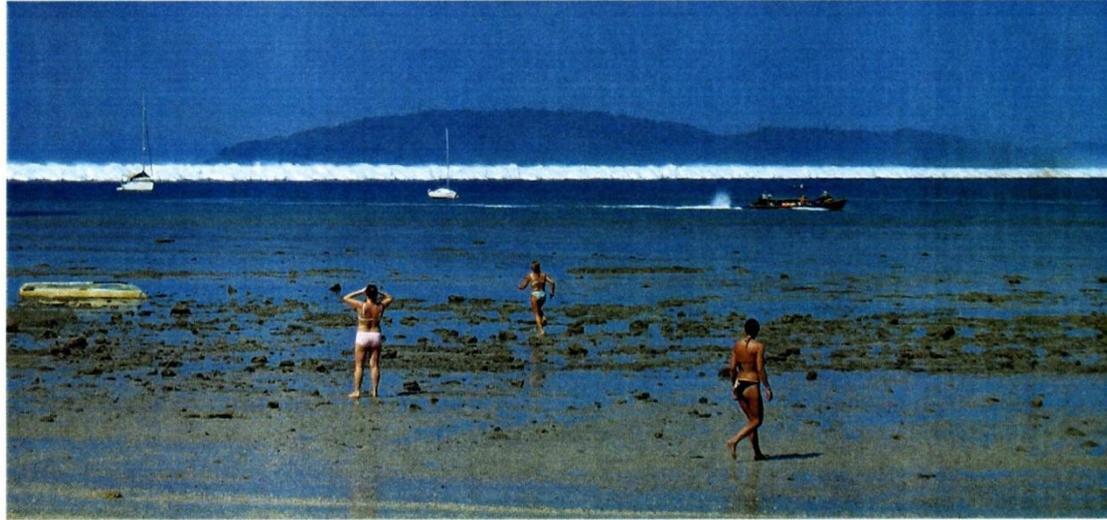


Fig.8 Two distant incoming tsunami

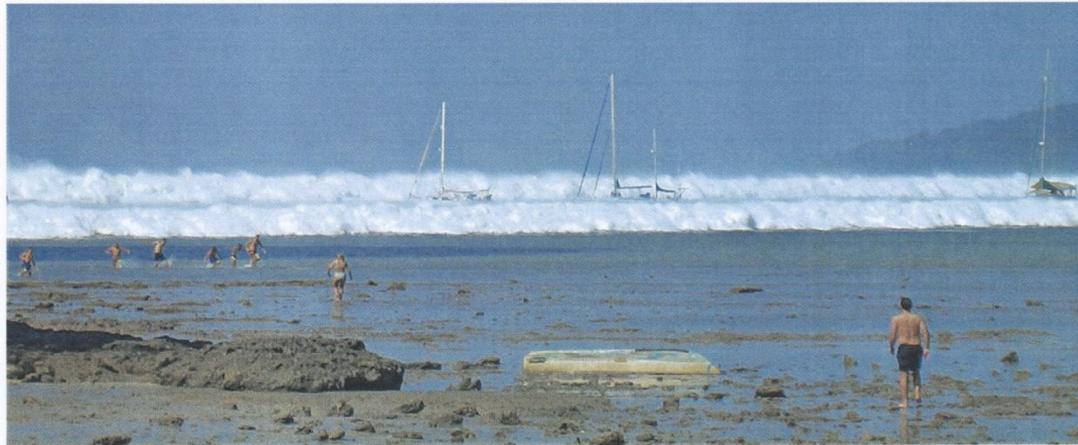


Fig.9 The two tsunami about to coalesce