



- When the ball is rolling it has kinetic energy K .

Since there is no slipping, $K = \text{const.}$, and the velocity of the ball is also $v_0 = \text{const.}$, ($\vec{v}_0 \neq \text{const.}$)

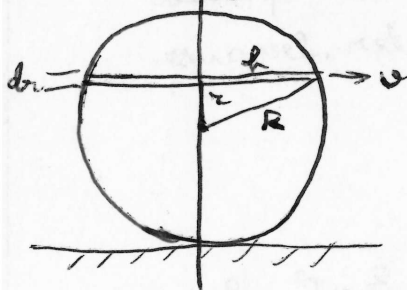
$$K = \frac{mv_0^2}{2} + \frac{I\omega^2}{2} = \frac{mv_0^2}{2} + \frac{2}{5}mR^2 \cdot \frac{1}{2} \cdot \frac{v_0^2}{R^2} = \left(\frac{1}{2} + \frac{1}{5}\right)mv_0^2 = \frac{7}{10}mv_0^2.$$

~~A~~

- The average velocity of all the points of the ball is \vec{v}_0 , the velocity of the center, so the total force on the ball created by the magnetic field is $\vec{F} = q\vec{v}_0 \times \vec{B}$, $|\vec{F}| = F$

$$F = qv_0B \quad (\text{just as for a point-like particle})$$

- However the magnetic field creates a torque τ on the ball.



all points that are a distance z above the center move with the same horizontal velocity $v = v_0 + v_0 \frac{z}{R} = v_0 \left(1 + \frac{z}{R}\right)$, and so have the same Ampere's force acting on them.

$$dF = vB dq, \quad dq = q \cdot \frac{dV}{V} = q \cdot \frac{\pi h^2 \cdot dz}{\frac{4}{3}\pi R^3} = \frac{3}{4}q \frac{h^2 dz}{R^3} = \frac{3}{4}q \frac{h^2}{R^3} dz = \frac{3}{4}q \frac{R^2 - z^2}{R^3} dz$$

Denote $\frac{z}{R} = x$: $dq = q \cdot \frac{3}{4}(1-x^2) dx$, $v = v_0(1+x)$

$$dF = v_0(1+x)B \cdot q \cdot \frac{3}{4}(1-x^2) dx = qv_0B \cdot \frac{3}{4}(1+x)(1-x^2) dx$$

$$d\tau = dF \cdot z = qv_0B \cdot \frac{3}{4}R x(1+x)(1-x^2) dx$$

$$\tau = \frac{3}{4}qv_0BR \int_{-1}^1 x(1+x)(1-x^2) dx \quad (\text{integrate from } z=-R \text{ to } z=R)$$



$$\int_{-1}^1 x(x+1)(1-x^2) dx = \int_{-1}^1 (1+x-x^2-x^3)x dx = \int_{-1}^1 (x+x^2-x^3-x^4) dx =$$

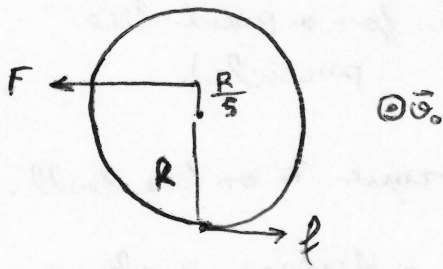
$$= \left[\frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} - \frac{x^5}{5} \right]_{-1}^1 = \left(\frac{1}{2} + \frac{1}{3} - \frac{1}{4} - \frac{1}{5} \right) - \left(\frac{1}{2} - \frac{1}{3} - \frac{1}{4} + \frac{1}{5} \right) =$$

$$= \frac{1}{2} + \frac{1}{3} - \frac{1}{4} - \frac{1}{5} - \frac{1}{2} + \frac{1}{3} + \frac{1}{4} - \frac{1}{5} = 2 \left(\frac{1}{3} - \frac{1}{5} \right) = 2 \cdot \frac{5-3}{3 \cdot 5} = \frac{4}{15}$$

$$\text{So } \tau = \frac{2}{15} q v_0 B R \cdot \frac{4}{15} = \frac{1}{5} q v_0 B R.$$

- In order for the ball to not slip there has to be a certain torque on it, which changes it's direction of rolling.

Let's look at the ball from the front:



the only other ~~force~~ ^{torque} on the ball is created by friction force f .

(τ is such as if F would be applied at $\frac{R}{5}$ above the center, because $\tau = \frac{1}{5} q v_0 B R = \frac{R}{5} \cdot F$)

$$\begin{cases} ma = F - f \\ \tau_{\text{tot}} = J\epsilon = \tau + fR = \frac{R}{5} F + fR \end{cases} \quad (J\epsilon = \frac{2}{5} mR^2 \cdot \frac{a}{R})$$

$$\frac{2}{5} mR \cdot a = \left(\frac{F}{5} + f \right) R$$

$$\frac{2}{5} ma - \frac{F}{5} = f \Rightarrow ma = F - \left(\frac{2}{5} ma - \frac{F}{5} \right)$$

$$ma = F - \frac{2}{5} ma + \frac{F}{5}$$

$$ma \left(1 + \frac{2}{5} \right) = F \left(1 + \frac{1}{5} \right)$$

$$\frac{7}{5} ma = \frac{6}{5} F$$

$7ma = 6F$, where a is the acceleration of the center of the ball.



Since the velocity $v_0 = \text{const.}$ and all forces are \perp perpendicular to \vec{v}_0 and constant, we can conclude that the ball will have a circular motion, described only by the velocity v_0 and radius R_0 .

$$\left. \begin{array}{l} a = \frac{v_0^2}{R_0} \\ \Gamma m a = G F = G q v_0 B \end{array} \right\}$$

$$\Gamma m \frac{v_0^2}{R_0} = G q v_0 B$$

$$\underline{\underline{R_0 = \frac{\Gamma m v_0}{G q B}}}$$