

As a function of  $x$  the center of mass height is

$$h_{CM} = -\left(l \cos \alpha + (l-x) \cos \alpha + \frac{x}{3} \cos \alpha\right) = -\left(2l - \frac{2x}{3}\right) \cos \alpha$$

And the total mass  $m$  is  $m = \rho L l^2 \sin \alpha \cos \alpha$

Where  $\alpha$  is the equilibrium angle, since  $m$  is constant:

$$m = \rho L x^2 \sin \alpha \cos \alpha \Rightarrow x^2 = \frac{m}{\rho L \sin \alpha \cos \alpha} = l^2 \frac{\sin \alpha \cos \alpha}{\sin \alpha \cos \alpha} = l^2 \frac{\sin 2\alpha}{\sin 2\alpha}$$

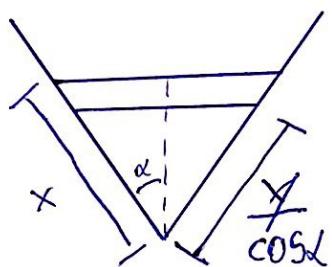
$$\Rightarrow x = l \sqrt{\frac{\sin(2\alpha)}{\sin(2\alpha)}} , \text{ Since potential energy is } U = mgh_{CM}$$

$$\Rightarrow U = -mg \left(2l - \frac{2x}{3}\right) \cos \alpha = -2mg l \left(1 - \frac{1}{3} \sqrt{\frac{\sin(2\alpha)}{\sin(2\alpha)}}\right) \cos \alpha$$

At equilibrium  $\frac{dU}{d\alpha} = 0 \Rightarrow$  Using Wolfram we find  $\sin \alpha = \frac{1}{\sqrt{6}}$ , therefore

the angle between the plates is  $2\alpha = 2 \arcsin\left(\frac{1}{\sqrt{6}}\right) \approx$

For the period of oscillation let us calculate the kinetic energy of the system using the figure below:



Drawing a set of horizontal lines we have that the distance between these lines is invariant, therefore:

$$\frac{y}{x \cos \alpha} = C \Rightarrow \frac{y}{\cos \alpha} \sqrt{\sin 2\alpha} = C \quad \text{Therefore } y \sqrt{\tan \alpha} = C$$

$\Leftrightarrow \text{constant}$

$$\text{Since } y \sqrt{\tan \alpha} = C \Rightarrow \frac{d(y \sqrt{\tan \alpha})}{dt} = 0 \Rightarrow \dot{y} \sqrt{\tan \alpha} + y \frac{d(\sqrt{\tan \alpha})}{dt} \cdot \frac{\dot{\alpha}}{\cos \alpha} = 0$$

$$\Rightarrow \dot{y} \sqrt{\tan \alpha} + \frac{y}{2} \frac{\dot{\alpha}}{\sqrt{\tan \alpha} \cos^2 \alpha} = 0 \Rightarrow \dot{y} = -\frac{\dot{\alpha} y}{2 \sin \alpha \cos \alpha} = -\frac{\dot{\alpha} y}{\sin 2\alpha}$$

Note that this velocity is relative to the bottom vertex, which has  $y$  coordinate  $2l \cos \alpha$  and moves with velocity  $v = 2l \dot{\alpha} \sin \alpha$

By conservation of volume  $\nabla \cdot \vec{v} = 0$ , where  $\vec{v}$  is liquid velocity, where

$$\vec{v} = \dot{x} \hat{x} + \dot{y} \hat{y}, \text{ this manner } \frac{\partial \dot{x}}{\partial x} + \frac{\partial \dot{y}}{\partial y} = 0 \Rightarrow \frac{\partial \dot{x}}{\partial x} = \frac{\dot{y}}{\sin(2\alpha)} \Rightarrow \dot{x} = \frac{\dot{y} x}{\sin 2\alpha}$$

For the kinetic energy associated to the x-axis we have:

$$d\bar{T}_x = \frac{\rho L dx dy \dot{x}^2}{2} \Rightarrow \bar{T}_x = \frac{\rho L}{2} \int_0^{l \cos \alpha} \int_{-ytan\alpha}^{ytan\alpha} \frac{\dot{y}^2 x^2}{\sin^2(2\alpha)} dx dy = \frac{\rho L \dot{x}^2}{2 \sin^2(2\alpha)} \int_0^{l \cos \alpha} \int_{-ytan\alpha}^{ytan\alpha} \frac{2y^3 \tan^3 \alpha}{3} dy dx$$

$$\Rightarrow \bar{T}_x = \frac{\rho L \dot{x}^2}{3 \sin^2(2\alpha)} \tan^3 \alpha \cdot \frac{l^4 \cos^4 \alpha}{4} = \frac{\rho L \dot{x}^2 l^4}{48 \sin^2 \alpha} \cdot \frac{\sin^3 \alpha}{\cos^3 \alpha} \cdot \frac{\cos^4 \alpha}{\cos^2 \alpha} = \frac{\rho L \dot{x}^2 l^4}{48} \tan \alpha$$

For the y axis we have that the velocity with respect to the lab frame:

$$v_y = v - \dot{y} = \dot{y} \left( 2l \sin \alpha - \frac{y}{\sin(2\alpha)} \right), \text{ so } d\bar{T}_y = \frac{\rho L dx dy}{2} v_y^2$$

$$\Rightarrow \bar{T}_y = \frac{\rho L \dot{x}^2}{2} \int_0^{l \cos \alpha} \int_{-ytan\alpha}^{ytan\alpha} \left( 2l \sin \alpha - \frac{y}{\sin(2\alpha)} \right)^2 dy dx = \frac{\rho L \dot{x}^2}{2} \int_0^{l \cos \alpha} 2ytan\alpha \left( 2l \sin \alpha - \frac{y}{\sin(2\alpha)} \right)^2 dy$$

$$\Rightarrow \bar{T}_y = \rho L \dot{x}^2 \tan \alpha \int_0^{l \cos \alpha} y \left( 2l \sin \alpha - \frac{y}{\sin(2\alpha)} \right)^2 dy = \rho L \dot{x}^2 \tan \alpha \cdot \frac{5l^4}{144} = \frac{\rho L l^4 \dot{x}^2 \tan \alpha}{144}$$

So the total Kinetic energy is  $\bar{T} = \bar{T}_x + \bar{T}_y = \rho L \dot{x}^2 l^4 \tan \alpha \left( \frac{1}{48} + \frac{5}{144} \right)$

$$\Rightarrow \bar{T} = \frac{\rho L \dot{x}^2 l^4 \tan \alpha}{144} \cdot 8 = \frac{\rho L l^4 \dot{x}^2 \tan \alpha}{18}, \text{ since } \sin \alpha = \frac{1}{\sqrt{6}}, \cos \alpha = \sqrt{\frac{5}{6}} \Rightarrow \tan \alpha = \frac{1}{\sqrt{5}}$$

$$\bar{T} = \frac{\rho L l^4 \dot{x}^2 \tan \alpha}{18 \sqrt{5}}$$

Since the energy is  $U(x) = U(d_0) + U'(d_0)(x-d_0) + U''(d_0)(x-d_0)^2 \approx U(d_0) + U''(d_0) \frac{\Delta^2}{2}$

where  $\Delta = d - d_0$ , and  $U = mg h_m \Rightarrow U'' = mg h_m''$

Since  $h_m = -(2l - \frac{2x}{3}) \cos \alpha \Rightarrow h'' = 4l \sqrt{\frac{6}{5}} \Rightarrow U'' = g \rho L l^2 \sin \alpha \cos \alpha \cdot 4l \sqrt{\frac{6}{5}}$

$$\Rightarrow \text{Therefore } U(\omega) = U(d_0) + \frac{\omega^2 \Delta^2}{2} = U(d_0) + 2\pi g L l^3 \sin \alpha \cos \alpha \sqrt{\frac{6}{5}} \Delta^2$$

$$\text{So } \omega^2 = 2\pi g L l^3 \sin \alpha \cos \alpha \sqrt{\frac{6}{5}} \cdot \frac{1}{\cancel{\pi} l^4 \cancel{\omega}^2} = \frac{g}{l} \cdot \sin \alpha \cos \alpha \sqrt{\frac{6}{5}} \cdot 18\sqrt{5} \cdot 2$$

$$\Rightarrow \omega^2 = \frac{g}{l} \cdot \frac{1}{\sqrt{6}} \cdot \sqrt{\frac{5}{6}} \cdot 18 \cdot 2\sqrt{5} = \frac{g}{l} \cdot 36 \sqrt{\frac{5}{6}} \Rightarrow \omega = \sqrt{\frac{g}{l}} \cdot 6 \sqrt{\sqrt{\frac{5}{6}}}$$

$$\omega^2 = 6 \frac{g}{l} \cdot \sqrt{\sqrt{\frac{5}{6}}} = \frac{6g}{l} \left(\frac{5}{6}\right)^{1/4} \Rightarrow 5,7327 \sqrt{\frac{g}{l}}$$

$$\text{So } 2\alpha = 2 \arcsin \left( \frac{1}{\sqrt{6}} \right) \approx 48,1897 \quad \text{and } \omega = 5,7327 \sqrt{\frac{g}{l}}$$