

Physics Cup - TalTech 2019, Felix Bekir Christensen

Problem 1

As the liquid is initially vortex free, it is vortex free at all times. $\oint \vec{V} d\vec{r} = 0 \quad \forall c \Leftrightarrow \nabla \times \vec{V} = 0$ By Stokes' theorem.

Furthermore $\nabla \cdot \vec{V} = 0$ as the fluid is incompressible.

As no liquid can flow into or out of the body, \vec{V} is purely tangential to its surfaces, i.e. $(\vec{V} - \vec{u}) \cdot \hat{n} = 0$ on S, where \vec{u} is the velocity of the body and \hat{n} is the unit normal to its surface. Finally, $\vec{V} \rightarrow 0$ very far away from the body, as otherwise the total energy of the liquid $T = \int \frac{1}{2} \rho |\vec{V}|^2 dV$ would not be finite. (As it is clearly finite initially, it has to stay finite at all times.) In summary: (All for a fixed moment in time, t)

$$\nabla \cdot \vec{V} = 0 \quad (1)$$

$$\nabla \times \vec{V} = 0 \quad (2)$$

$$(\vec{V} - \vec{u}) \cdot \hat{n} = 0 \text{ on } S \quad (3)$$

$$\vec{V} \rightarrow 0 \text{ far from } S \quad (4)$$

~~$$\frac{dE}{dV} = \frac{1}{2} \rho |\vec{V}|^2 \quad (5)$$~~

Of course (1)-(3) are only valid outside of the body.

Now consider putting the body in a constant E-field \vec{E}_0 and then "freezing" its polarisation and removing the field. For simplicity, let \vec{E}_0 and \vec{u} have the same direction, the positive X-direction. Note that the total charge on the sphere is zero and hence all surface charges are bound charges. Let us examine the resulting field. (We assume that there is no B-field)

We are given the information that if the body were made of a dielectric and placed in a homogeneous E-field, the field inside it would be homogeneous as well. As inside a dielectric, $\vec{P} = \chi \epsilon_0 \vec{E}$ where \vec{P} is the polarisation density, it follows, that if the body is polarised, \vec{P} is homogeneous. So we can simply write $\vec{P} = \frac{\vec{p}}{V}$ where (lower case) \vec{p} is the dipole moment. But $\vec{p} = d \vec{E}_0$, so simply $\vec{P} = \frac{d}{V} \vec{E}_0$ everywhere inside the body. (6)

The E-field inside a conductor is always zero, so the field inside the polarised body is $-\vec{E}_0$. This lets us calculate the electric displacement field inside the body. As $\vec{D} = \epsilon_0 \vec{E} + \vec{P}$, we get:

$$\vec{D}_0 = -\epsilon_0 \vec{E}_0 + \frac{d}{V} \vec{E}_0$$

$$(7) \quad \vec{D}_0 = \left(\frac{d}{V} - \epsilon_0 \right) \vec{E}_0$$

Outside the body, we have by Gauss and Faraday's laws:

$$\nabla \cdot \vec{E} = 0 \quad (8) \quad (\text{no charge})$$

$$\nabla \times \vec{E} = 0 \quad (9) \quad (\text{no time-dependent B-field})$$

At the air-body boundary, notice that there are no free charges, so the normal component of \vec{D} stays continuous.

Outside the body, $\vec{D} = \epsilon_0 \vec{E}$, so:

$$\epsilon_0 \vec{E} \cdot \hat{n} = \left(\frac{d}{V} - \epsilon_0 \right) \vec{E}_0 \cdot \hat{n}$$

~~$$(\vec{E} - \left(\frac{d}{\epsilon_0 V} - 1 \right) \vec{E}_0) \cdot \hat{n} = 0$$~~

$$(10) \quad (\text{on S})$$

For away from all charges, the E-field vanishes, ie.

~~$$\vec{E} \rightarrow 0 \text{ far from S}$$~~

$$(11)$$

Finally, the energy density of an electric field is

$$\frac{dU}{dV} = \frac{1}{2} \epsilon_0 |\vec{E}|^2 \quad (12)$$

Comparing eqs. (1)-(5) with (8)-(12) we see that we have successfully restated the original fluid dynamics problem as an electrostatics one. Let us now find the energy of the surface charge configuration; The surface charge density is given by:

$$\sigma = \vec{P} \cdot \hat{n}$$

$$(13) \quad \sigma = \frac{\alpha}{V} \vec{E}_0 \cdot \hat{n}$$

Let the potential be zero at some point P inside the body.

Then, the potential at Q inside the body is simply $\phi = X |\vec{E}_0|$ (14)

where X is the difference of the X-coordinates of Q and P, $X = (\vec{q} - \vec{p}) \cdot \hat{x}$.

(Recall that the direction of the field inside the body is the negative X-direction as it is $-\vec{E}_0$)

The potential energy of a charge distribution is $U = \int \frac{1}{2} \rho \phi dV$

hence for our surface charge configuration $U = \frac{1}{2} \oint_S \sigma \phi dA$ | Use (13) and (14)

$$\Rightarrow U = \frac{\alpha |\vec{E}_0|}{2V} \oint_S \vec{E}_0 \cdot \hat{n} dA \quad | \vec{E}_0 = |\vec{E}_0| \hat{x}$$

$$\Leftrightarrow U = \frac{\alpha |\vec{E}_0|^2}{2V} \oint_S \hat{x} \cdot \hat{n} dA \quad | \text{ Use Gauss' law with } \nabla \cdot (\hat{x} \hat{x}) = 1$$

$$\Leftrightarrow U = \frac{\alpha |\vec{E}_0|^2}{2V} \int V dV$$

$$\Leftrightarrow U = \frac{\alpha |\vec{E}_0|^2 \cdot V}{2V}$$

$$\Leftrightarrow U = \frac{\alpha |\vec{E}_0|^2}{2} \quad (15)$$

$$\text{But also } U = \int_{\text{all space}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV = \int_{\text{inside body}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV + \int_{\text{outside body}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV$$

$$\text{As inside the body; } \vec{E} = -\vec{E}_0 \text{ we get } \int_{\text{inside body}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV = \frac{1}{2} \epsilon_0 |\vec{E}_0|^2 V$$

so

$$\int_{\text{outside body}} \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV = U - \frac{1}{2} \epsilon_0 |\vec{E}_0|^2 V$$

$$\Leftrightarrow \int \frac{1}{2} \epsilon_0 |\vec{E}|^2 dV = (\alpha - \epsilon_0 V) \frac{|\vec{E}_0|^2}{2} \quad (16)$$

outside body

Now compare eqs. (5) and (12). The velocity field of the fluid and the E-field have the same Energy density whence

$$\frac{1}{2} \rho |\vec{V}|^2 = \frac{1}{2} \epsilon_0 |\vec{E}|^2$$

$$\Leftrightarrow |\vec{E}|^2 = \frac{\rho}{\epsilon_0} |\vec{V}|^2 \quad (17)$$

Scaling the boundary condition (3), (10) similarly gives:

$$(\frac{\alpha}{\epsilon_0} - 1)^2 |\vec{E}_0|^2 = \frac{\rho}{\epsilon_0} |\vec{U}|^2$$

$$\Leftrightarrow |\vec{E}_0|^2 = \frac{\rho |\vec{U}|^2}{\epsilon_0 (\frac{\alpha}{\epsilon_0} - 1)^2} \quad (18)$$

The kinetic energy of the liquid is just its energy density integrated over its volume (that is, outside of the body):

$$T = \int \frac{1}{2} \rho |\vec{V}|^2 dV \quad (19)$$

outside body

But this equals the integral in (16) if (18) is satisfied:

$$\Rightarrow T = (\alpha - \epsilon_0 V) \frac{|\vec{E}_0|^2}{2}$$

$$\Rightarrow T \stackrel{(18)}{=} \frac{1}{2} (\alpha - \epsilon_0 V) \frac{\rho |\vec{U}|^2}{\epsilon_0 (\frac{\alpha}{\epsilon_0} - 1)^2}$$

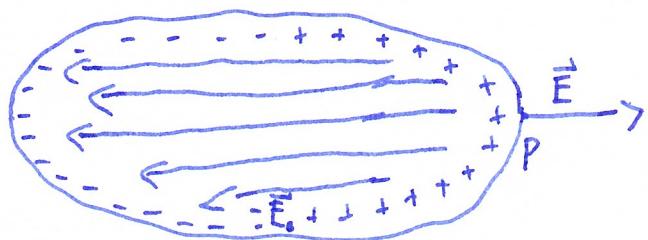
$$\Leftrightarrow T = \frac{1}{2} \cdot \frac{\epsilon_0 V^2 \rho}{\alpha - \epsilon_0 V} |\vec{U}|^2 \quad (20)$$

Finally giving an expression resembling the well-known K.e. formula $T = \frac{1}{2} m |\vec{U}|^2$. Comparing this to (20) then gives the added mass:

$$m_{\text{add}} = \frac{\epsilon_0 V^2 \rho}{\alpha - \epsilon_0 V}$$

One might wonder about the possibility of this expression being negative, which would be unphysical. But the inequality $d - \epsilon_0 V > 0$ which implies $m_{\text{add}} > 0$ can be motivated as follows:

The charge distribution looks roughly like this:



The direction of \vec{E} at P is the positive x-direction as the positive charges are much closer to P than the negative ones. As $\vec{D} = \epsilon_0 \vec{E}$, the direction of \vec{D} at P is also the positive x-direction. Recall that $\vec{D} \cdot \hat{n}$ is continuous at the boundary, so \vec{D}_0 must point in the ~~pos~~ same direction. But by (7) this is the case iff

$$\frac{d}{V} - \epsilon_0 > 0 \quad (\text{As } \vec{E}_0 \text{ points in the positive x-direction})$$

$$\Leftrightarrow d - \epsilon_0 V > 0$$