

2.11.6 Elementaarpinna muutumise kiirus

Lõpmata väiked vektorid $d\mathbf{X}_{(1)} = dX_{(1)}^L \mathbf{G}_L$ ja $d\mathbf{X}_{(2)} = dX_{(2)}^M \mathbf{G}_M$ † LK-s (või $d\mathbf{x}_{(1)} = dx_{(1)}^l \mathbf{g}_l$ ja $d\mathbf{x}_{(2)} = dx_{(2)}^m \mathbf{g}_m$ EK-s) määravad läbi vektorkorrutise elamentaarpinnad

$$d\mathbf{A} = d\mathbf{X}_{(1)} \times d\mathbf{X}_{(2)} \quad \text{ja} \quad d\mathbf{a} = d\mathbf{x}_{(1)} \times d\mathbf{x}_{(2)}, \quad (2.335)$$

mida saab omakorda avaldada läbi kontravariantse baasi kujul

$$d\mathbf{A} = dA_K \mathbf{G}^K \quad \text{ja} \quad d\mathbf{a} = da_k \mathbf{g}^k, \quad (2.336)$$

$$\begin{aligned} dA_K &= d\mathbf{A} \cdot \mathbf{G}_K = (dX_{(1)}^L \mathbf{G}_L \times dX_{(2)}^M \mathbf{G}_M) \cdot \mathbf{G}_K = \\ &= dX_{(1)}^L dX_{(2)}^M \underbrace{(\mathbf{G}_L \times \mathbf{G}_M)}_{\epsilon_{LMN} \mathbf{G}^N} \cdot \mathbf{G}_K = \dots = \end{aligned} \quad (2.337)$$

$$\begin{aligned} &= \epsilon_{LMN} \delta^N_K dX_{(1)}^L dX_{(2)}^M = \epsilon_{LMK} dX_{(1)}^L dX_{(2)}^M; \\ da_k &= \dots = \epsilon_{lmk} dx_{(1)}^l dx_{(2)}^m. \end{aligned}$$

Elementaarpinna vektorite $d\mathbf{A}$ ja $d\mathbf{a}$ kovariantsed komponendid saab omakorda avaldada bivektorite dA^{LM} ja da^{lm} kujul: ‡

$$\begin{aligned} dA^{LM} &= \epsilon^{KLM} dA_K, \quad dA_K = \frac{1}{2} \epsilon_{KLM} dA^{LM}, \\ da^{lm} &= \epsilon^{klm} da_k, \quad da_k = \frac{1}{2} \epsilon_{klm} da^{lm}. \end{aligned} \quad (2.338)$$

Kuna $\epsilon_{LMK} = \epsilon_{KLM}$ ja $\epsilon_{lmk} = \epsilon_{klm}$, siis (2.337) ja (2.338) põhjal

$$dA^{LM} = 2dX_{(1)}^L dX_{(2)}^M \quad \text{ja} \quad da^{lm} = 2dx_{(1)}^l dx_{(2)}^m. \quad (2.339)$$

Deformatsiooni käigus $dX^K \rightarrow dx^k = x^k_{,K} dX^K$. Seega

$$da^{kl} = 2dx_{(1)}^k dx_{(2)}^l = 2x^k_{,K} dX_{(1)}^K x^l_{,L} dX_{(2)}^L \stackrel{(2.339)}{=} x^k_{,K} x^l_{,L} dA^{KL}. \quad (2.340)$$

Rakendades (2.338) saame minna tagasi elementaarpinna vektorite komponentidele

$$da_k = \frac{1}{2} \epsilon_{klm} x^l_{,L} x^m_{,M} dA^{LM} = \frac{1}{2} \epsilon_{klm} \epsilon^{KLM} x^l_{,L} x^m_{,M} dA_K. \quad (2.341)$$

Kuna saab näidata, et (vt. Eringeni ja Narasimhani õpikud)

$$\epsilon^{KLM} \epsilon_{klm} x^l_{,L} x^m_{,M} = 2JX^K_{,k} \quad \text{ja} \quad J = \sqrt{\frac{g}{G}} j, \quad (2.342)$$

siis

$$da_k = JX^K_{,k} dA_K \quad \text{ja} \quad dA_K = J^{-1} x^k_{,K} da_k. \quad (2.343)$$

Seega, materiaalne tuletis pinnaelemendist

$$\frac{D(da_k)}{Dt} = \frac{D(JX^K_{,k} dA_K)}{Dt} = \left[\frac{DJ}{Dt} X^K_{,k} + J \frac{D(X^K_{,k})}{Dt} \right] dA_K. \quad (2.344)$$

Materiaalne tuletis $\frac{DJ}{Dt} = Jv^m_{;m}$ kuid $\frac{D(X^K_{,k})}{Dt}$ määramiseks leiame materiaalse tuletise avaldisest $x^k_{,K} X^K_{,l} = \delta^k_l$: ✓

$$\begin{aligned} x^k_{,K} \frac{D(X^K_{,l})}{Dt} &= -\frac{D(x^k_{,K})}{Dt} X^K_{,l} \Big| \cdot X^L_{,k} \Rightarrow \\ \frac{D(X^K_{,l})}{Dt} x^k_{,K} X^L_{,k} &= -\frac{D(x^k_{,K})}{Dt} X^K_{,l} X^L_{,k} \\ \frac{D(X^K_{,l})}{Dt} \delta_K^L &= -v^k_{;m} x^m_{,K} X^K_{,l} X^L_{,k} \\ \frac{D(X^L_{,l})}{Dt} &= -v^k_{;m} \delta^m_l X^L_{,k} = -v^k_{;l} X^L_{,k}. \end{aligned}$$

Tähistades indeksid ümber, saame kokkuvõttes

$$\frac{D(X^K_{,k})}{Dt} = -X^K_{,l} v^l_{;k} \quad (2.345)$$

Avaldisest (2.344) saame nüüd

$$\begin{aligned} \frac{D(da_k)}{Dt} &= [Jv^m_{;m} X^K_{,k} - JX^K_{,l} v^l_{;k}] dA_K = \\ &= v^m_{;m} \underbrace{JX^K_{,k} dA_K}_{=da_k} - v^l_{;k} \underbrace{JX^K_{,l} dA_K}_{=da_l}. \end{aligned}$$

Seega avaldub pinnaelemendi materiaalne tuletis (muutumise kiirus) kujul

$$\frac{D(da_k)}{Dt} = v^m_{;m} da_k - v^m_{;k} da_m. \quad (2.346)$$