

ITB8832 Mathematics for Computer Science

Lecture 3 – 18 September 2023

Chapter Three

Equivalence and Validity

The Algebra of Propositions

The SAT problem

Predicate Formulas

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- 1 Equivalence and Validity
- 2 The Algebra of Propositions
- 3 The SAT problem
- 4 Predicate Logic

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1 Equivalence and Validity

2 The Algebra of Propositions

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Contrapositives

Definition

The *contrapositive* of the formula P implies Q is the formula $\text{not}(Q)$ implies $\text{not}(P)$.

Contrapositives are equivalent to each other.

P	Q	P implies Q	$\text{not}(Q)$	implies	$\text{not}(P)$
T	T	T	F	T	F
T	F	F	T	F	F
F	T	T	F	T	T
F	F	T	T	T	T

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For example,

If I am hungry, then I am grumpy

is equivalent to

If I am not grumpy, then I am not hungry

Converses

Definition

The *converse* of the formula P implies Q is the formula Q implies P .

Converses *are not* equivalent to each other!

P	Q	P implies Q	Q implies P
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However, *conjunction of converses is equivalent to iff*.

P	Q	P implies Q	and	Q implies P	P iff Q
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F	T	T	F	F	F
F	F	T	T	T	T

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However, *conjunction of converses is equivalent to iff*.

For example,

If I am hungry, then I am grumpy, and if I am grumpy, then I am hungry

is equivalent to

I am grumpy if and only if I am hungry

Validity

Definition

A propositional formula is *valid* if it is true for *every* assignment of truth values to its variables.

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Examples:

- $\text{not}(P \text{ and } \text{not}(P))$ *law of non-contradiction*
- $P \text{ or } \text{not}(P)$ *law of excluded middle*
- $P \text{ iff } \text{not}(\text{not}(P))$ *double negation*
- $P \text{ implies } (Q \text{ implies } P)$ *weakening*
- $(P \rightarrow (Q \rightarrow R)) \rightarrow ((P \rightarrow Q) \rightarrow (P \rightarrow R))$ *conditional modus ponens*

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Non-example:

- P , where P is any propositional variable.

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- P , where P is a propositional variable.
That is: every atomic formula is satisfiable.
- $P \otimes Q$, where P and Q are variables and \otimes is any of the binary connectives and, or, implies, iff, and xor.

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Non-example:

- A and not(A), where A is any formula.

Validity, satisfiability, and equivalence

Let P and Q be formulas.

Theorem

P is valid if and only if $\text{not}(P)$ is unsatisfiable.

P is satisfiable if and only if $\text{not}(P)$ is not valid.

Theorem

P and Q are equivalent if and only if P iff Q is valid.

Next section

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- 2 The Algebra of Propositions**
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Disjunctive normal forms: An example

Let $\phi ::= A \text{ and } (B \text{ or } C)$. Consider its truth table:

A	B	C	ϕ
T	T	T	T
T	T	F	T
T	F	T	T
T	F	F	F
F	T	T	F
F	T	F	F
F	F	T	F
F	F	F	F

The assignments of (A, B, C) which make ϕ true are (T, T, T) , (T, T, F) , and (T, F, T) . These are the same assignments that make the following formula true:

$$(A \text{ and } B \text{ and } C) \text{ or } (A \text{ and } B \text{ and } \overline{C}) \text{ or } (A \text{ and } \overline{B} \text{ and } C)$$

Formulas in disjunctive normal form

Definition

- A *literal* is a symbol of the form A or \bar{A} where A is a propositional variable.
- An *and -clause* is a conjunction of literals where each variable appears at most once, either as itself or as its negation.
- A formula ψ in n variables P_1, \dots, P_n is in *disjunctive normal form (DNF)* if it is written as a disjunction of and -clauses.
- If every variable appears in every conjunction (either as itself or its negation) the DNF is said to be *full*.

For example, this formula is in DNF:

$$(A \text{ and } B \text{ and } C) \text{ or } (A \text{ and } B \text{ and } \bar{C}) \text{ or } (A \text{ and } \bar{B} \text{ and } C)$$

and so is this one:

$$(A \text{ and } B) \text{ or } (A \text{ and } \bar{B} \text{ and } C)$$

but these ones are not:

$$A \text{ and } (B \text{ or } C); A \text{ and } B \text{ and } C \text{ and } A; \text{ not}(A \text{ and } B \text{ and } C)$$

Disjunctive normal form(s) of a formula

Definition

A *disjunctive normal form* of a formula ϕ is a formula ψ in DNF which is equivalent to ϕ .

For example,

$$(A \text{ and } B \text{ and } C) \text{ or } (A \text{ and } B \text{ and } \overline{C}) \text{ or } (A \text{ and } \overline{B} \text{ and } C)$$

is a disjunctive normal form of

$$A \text{ and } (B \text{ or } C)$$

Existence of the DNF

Theorem

Every *satisfiable* propositional formula has a DNF.

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Every *satisfiable* propositional formula has a DNF.

Proof:

- Let P_1, \dots, P_n be the variables of the formula ϕ .
- Construct the truth table of ϕ .
- For each row where ϕ has value T, construct a conjunction (A_1 and ... and A_n) where:
 - $A_i = P_i$ if $P_i = T$ on the row;
 - $A_i = \text{not}(P_i)$ if $P_i = F$ on the row.
- The disjunction of all these conjunctions is a DNF for ϕ .

Satisfiability and DNF

The procedure in the previous slide constructs a DNF from the rows of the truth table where the formula is true.

- This presumes that there is at least one such row.
- But what if there is none?¹

A possible way out is to use the following convention:

The DNF of an unsatisfiable formula is empty.

This is a patch rather than a fix, because we did not define propositional formulas so that they could be empty.

¹Remarkably, the textbook says nothing about this.

Conjunctive normal forms

“Dually” to DNF, we have:

Definition

- An *or-clause* is a disjunction of literals where each variable appears at most once, either as itself or as its negation.
- A formula ψ in n variables P_1, \dots, P_n is in *conjunctive normal form (CNF)* if it is written as a conjunction of or-clauses.
- If every variable appears in every conjunction (either as itself or its negation) the CNF is said to be *full*.
- A *conjunctive normal form* of a formula ϕ is a formula ψ in CNF which is equivalent to ϕ .

Theorem

Every *non-valid* propositional formula has a CNF.

Exercise: Modify the algorithm to derive the full DNF of a satisfiable formula to obtain an algorithm that derives the full CNF of a non-valid formula.

An algebra for propositional calculus

George Boole (1815-1864) defined a set of rules for manipulating propositional formula, which are now known as *Boolean algebra*.

- These rules are given as equivalence between propositional formulas constructed via the connectives \wedge , \vee , and \neg .
- The reason is that \wedge , \vee , and \neg form a *basis of connectives*: Every propositional formula is equivalent to a formula where the only connectives are \wedge , \vee , and \neg .
(For example: a DNF if it is satisfiable, or a CNF if it is not valid.)

The first axiom is the *law of double negation*:

$$\neg(\neg A) \longleftrightarrow A$$

An algebra for the propositional calculus: and

The following formulas are all valid:

$A \wedge B$	\longleftrightarrow	$B \wedge A$	commutativity
$(A \wedge B) \wedge C$	\longleftrightarrow	$A \wedge (B \wedge C)$	associativity
$A \wedge A$	\longleftrightarrow	A	idempotence
$A \wedge T$	\longleftrightarrow	A	identity
$A \wedge F$	\longleftrightarrow	F	zero
$A \wedge \overline{A}$	\longleftrightarrow	F	noncontradiction
$A \wedge (B \vee C)$	\longleftrightarrow	$(A \wedge B) \vee (A \wedge C)$	distributivity
$A \wedge (B \vee A)$	\longleftrightarrow	A	absorption
$\neg(A \wedge B)$	\longleftrightarrow	$\overline{A} \vee \overline{B}$	de Morgan's law

An algebra for the propositional calculus: or

The following formulas are all valid:

$A \vee B$	\longleftrightarrow	$B \vee A$	commutativity
$(A \vee B) \vee C$	\longleftrightarrow	$A \vee (B \vee C)$	associativity
$A \vee A$	\longleftrightarrow	A	idempotence
$A \vee F$	\longleftrightarrow	A	identity
$A \vee T$	\longleftrightarrow	T	unit
$A \vee \overline{A}$	\longleftrightarrow	T	excluded middle
$A \vee (B \wedge C)$	\longleftrightarrow	$(A \vee B) \wedge (A \vee C)$	distributivity
$A \vee (B \wedge A)$	\longleftrightarrow	A	absorption
$\neg(A \vee B)$	\longleftrightarrow	$\overline{A} \wedge \overline{B}$	de Morgan's law

A strategy for DNF

Let ϕ be an arbitrary propositional formula.

- 1 Apply *de Morgan's laws* until \neg is only applied to single variables.
- 2 Apply *distributivity* to obtain a disjunction of conjunctions.
- 3 Apply *idempotence* to remove multiple instances of variables within conjunctions.
- 4 Apply *associativity* to remove unnecessary parentheses.
- 5 Complete each conjunction so that, for each variable P , exactly one between P and \overline{P} appears in it.
To do this, exploit that $A \longleftrightarrow A \wedge (B \vee \overline{B})$ is a valid formula, following from $A \wedge \text{T} \longleftrightarrow A$ and $B \vee \overline{B} \longleftrightarrow \text{T}$.
- 6 Simplify the formula by using distributivity, commutativity, and absorption.

Completeness of propositional calculus

Theorem

Two propositional formulas *are* equivalent *if and only if* they *can be proved* to be equivalent via the axioms of Boolean algebra.

Proof: (sketch)

- *Simple*: As all the axioms of Boolean algebra are equivalences, so must be any proposition proved starting from them.
- *Complicated*: The axioms of Boolean algebra allow conversion to disjunctive normal form, and two formulas are equivalent iff they have the same DNF (up to commutativity).

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The Satisfiability problem

The *Satisfiability problem*, denoted as SAT, is:

Given an arbitrary Boolean formula ϕ ,
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How difficult can this be?

Conceptually: not much

- 1 Put ϕ in disjunctive normal form.
- 2 Use truth tables to determine if ϕ is true for some assignment of variables.

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Computationally: **A LOT**

- Suppose ϕ depends on n Boolean variables.
- If ϕ is not satisfiable, we need to test *each one of the 2^n truth assignments* to prove so.
- For $n = 50$ variables, with a computer capable of 1 million such tests per second, this takes *more than thirty-five years*.

Big Oh notation

Definition

Given two functions $f, g : \mathbb{N} \rightarrow [0, +\infty)$ we say that $f(n)$ is *big Oh of* $g(n)$, and write $f(n) = O(g(n))$, if there exist $n_0 \in \mathbb{N}$ and $C > 0$ such that

$$f(n) \leq C \cdot g(n) \text{ for every } n \geq n_0.$$

- If $T(n)$ is the maximum time required to solve SAT for a given formula, then $T(n) = O(2^n)$.
- Problems only solvable in exponential or larger time are considered to be *intractable*.

Polynomial time algorithms

Definition

An algorithm runs in *polynomial time* $T(n)$ in the size n of its input if $T(n) = O(n^k)$ for some $k \geq 1$.

The class of polynomial-time algorithms has some “good” features:

- Polynomials “do not grow too fast”.
- A *composition* of polynomials is still a polynomial:
If $p(x)$ and $q(x)$ are polynomials, then so is $p(q(x))$, what you obtain if you replace every occurrence of x with $q(x)$ in the expression of $p(x)$ and simplify.
- Hence, a composition of polynomial time algorithms is still a polynomial time algorithm.

P versus NP

Definition: P

The class P is the class of the decision problems that have a *solution algorithm* which runs in polynomial time in the size of the input.

That is: problem X is in class P if and only if there are a polynomial $p(t)$ and an algorithm A running in time $O(p(n))$ for inputs of size n which, however given in input an instance I of X , produces in output the YES/NO answer to I .

Definition: NP

The class NP is the class of the decision problems that have a *verification algorithm* which runs in polynomial time in the size of the input.

That is: problem X is in class NP if and only if there are a polynomial $p(t)$ and an algorithm A running in time $O(p(n))$ for inputs of size n which, however given in input an instance I of X *and a potential witness w that the answer to I is YES*, determines if w is really so.

P versus NP

Definition: P

The class P is the class of the decision problems that have a *solution algorithm* which runs in polynomial time in the size of the input.

Definition: NP

The class NP is the class of the decision problems that have a *verification algorithm* which runs in polynomial time in the size of the input.

The following happens:

- 1 SAT belongs to NP.
- 2 For every problem X in NP there exists an algorithm that turns any instance I of X and potential witness w of I into an instance J of SAT and a potential witness z of J , in time polynomial in the size of I and w , and so that the answer to I is YES if and only if the answer to J is YES.

Consequently:

If $\text{SAT} \in \text{P}$ then $\text{P} = \text{NP}$.

What if $P = NP$?

The good:

- We can efficiently *design circuits*.
- We get efficient algorithms for *scheduling*.
- We can efficiently *distribute resources*.

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- We can efficiently *design circuits*.
- We get efficient algorithms for *scheduling*.
- We can efficiently *distribute resources*.

The bad:

- Modern cryptography becomes *insecure*.

SAT solvers

There is currently a big interest in algorithms that, *under certain conditions*, solve SAT in polynomial time.

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Doesn't this presume that $\text{SAT} \in \text{P}$?

SAT solvers

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Question

Doesn't this presume that $\text{SAT} \in \text{P}$?

Answer: *no*, because

- even if *the problem as a whole* is not efficiently solvable,
- it might still be that *some well defined subclasses of cases* are.

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Truth for predicates

Consider a predicate of the form: $x^2 \geq 0$.

- This is always true if x is a *real* number.
- But if x is a *complex* number, it might be false:
- For example, $i^2 = -1 < 0$.
- Worse still, $\left(\frac{1}{2} + i\frac{\sqrt{3}}{2}\right)^2 = -\frac{1}{2} + i\frac{\sqrt{3}}{2}$ is not even a real number, and cannot be said to be “smaller” or “larger” than zero.

How can we specify *when* a predicate is true?

Universal quantifier

Let $P(x)$ be a predicate depending on a variable x which takes values in a set S (the *type* of the variable).

Definition

The formula:

$$\forall x \in S. P(x)$$

is true if and only if $P(x)$ is true for *every* $x \in S$.

The formula can be read as follows:

- For every x in S , $P(x)$.
- $P(x)$ is true for every x in S .

For example, the following formulas are true:

$$\forall x \in \mathbb{R}. x^2 \geq 0 ; \forall n \in \mathbb{N}. \text{if } n \text{ is prime then } \sqrt{n} \text{ is irrational}$$

but the following ones are false:

$$\forall x \in \mathbb{C}. x^2 \geq 0 ; \forall n \in \mathbb{N}. \sqrt{n} \text{ is irrational}$$

Existential quantifier

Let $P(x)$ be a predicate depending on a variable x which takes values in a set S (the *type* of the variable).

Definition

The formula:

$$\exists x \in S. P(x)$$

is true if and only if $P(x)$ is true for *at least one* $x \in S$.

The formula can be read as follows:

- There exists x in S such that $P(x)$.
- $P(x)$ is true for some x in S .

For example, the following formulas are true:

$$\exists x \in \mathbb{R}. 5x^2 = 7 ; \exists n \in \mathbb{N}. n^2 = 16$$

but the following ones are false:

$$\exists x \in \mathbb{R}. 5x^2 = -7 ; \exists n \in \mathbb{N}. n^2 = 17$$

Precedence of quantifiers

Quantifiers have a *stronger* binding than propositional connectives:

$\forall x. P(x)$ implies Q stands for $(\forall x. P(x))$ implies Q .

However, some textbooks (including ours) seem to *also* use the following convention:

A quantifier using a variable x binds as many instances of x as possible before encountering another quantifier.

Example from the textbook (page 67, formula (3.27))

- Textbook: $\exists x. \forall y. P(x, y)$ implies $\forall x. \exists y. P(x, y)$.
- Meaning: $(\exists x. \forall y. P(x, y))$ implies $(\forall x. \exists y. P(x, y))$.

Again: When in doubt, use parentheses.

If you can solve any exercise, then you will pass the test

Let $\text{solve}(x)$ be a predicate meaning that you solve exercise x .
Let pass be a proposition meaning that you pass the test.

You can pass the test by solving only one exercise

$(\exists x \in \text{Exercises} . \text{solve}(x)) \longrightarrow \text{pass}$

You can pass the test by solving one specific exercise

$\exists x \in \text{Exercises} . (\text{solve}(x) \longrightarrow \text{pass})$

You need to solve every single exercise to pass the test

$\text{pass} \longrightarrow \forall x \in \text{Exercises} . \text{solve}(x)$

Mixing quantifiers

Many mathematical statements involve more than one quantifier:

Goldbach's Conjecture

Every even integer larger than 2 is a sum of two primes.

If we define S as the set of the even integers larger than 2, Goldbach's conjecture can be expressed by the formula:

$$\forall n \in S. \exists p \in \text{Primes}. \exists q \in \text{Primes}. p + q = n$$

As p and q vary in the same set Primes, we can also use the more compact writing:

$$\forall n \in S. \exists p, q \in \text{Primes}. p + q = n$$

Everyone has a dream

Let $\text{dreams}(p, d)$ mean that person p has dream d .

Every single person has some dream

$\forall p \in \text{Persons} . \exists d \in \text{Dreams} . \text{dreams}(p, d)$

There is a single dream everyone has

$\exists d \in \text{Dreams} . \forall p \in \text{Persons} . \text{dreams}(p, d)$

De Morgan's laws for quantifiers

When the operator $\text{not}(\cdot)$ is applied to a predicate starting with a quantifier, the following happen:

$\text{not}(\forall x. P(x))$ is equivalent to $\exists x. \text{not}(P(x))$

$\text{not}(\exists x. P(x))$ is equivalent to $\forall x. \text{not}(P(x))$

Validity for predicate formulas

Intuitively, a predicate formula is valid if it is evaluated as true:

- no matter what the *domain* of the discourse is,
- no matter what the *type* of the variables are, and
- no matter what *interpretation* of its predicates is given.

This is *much harder* to formalize, and to verify, than validity of propositional formulas.

A valid predicate formula

Theorem

The following predicate formula is valid:

$$(\exists x. \forall y. P(x, y)) \text{ implies } (\forall y. \exists x. P(x, y))$$

Proof:

- If x varies in D and y varies in H , the formula becomes:

$$(\exists x \in D. \forall y \in H. P(x, y)) \text{ implies } (\forall y \in H. \exists x \in D. P(x, y))$$

- Suppose $\exists x \in D. \forall y \in H. P(x, y)$ is true:
We want to show that $\forall y \in H. \exists x \in D. P(x, y)$ is also true.
- Take $x_0 \in D$ such that $\forall y \in H. P(x_0, y)$ is true.
- If we are given $y \in H$, we can always find $x \in D$ such that $P(x, y)$ is true, simply by putting $x = x_0$.
- Then $\forall y \in H. \exists x \in D. P(x, y)$ is true, as we wanted.
- As the argument does not depend on the domain, types, and interpretation, the argument always works, and the predicate formula is valid.

Counter-models

Definition

Let $\phi(x_1, \dots, x_n)$ be a predicative formula depending on the n variables x_i .

A *counter-model* for ϕ is a choice of:

- a domain D ,
- types S_i for the variables x_i , and
- interpretations in D for the predicates occurring in ϕ

that make ϕ *false*.

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that make ϕ *false*.

Counter-models are at least as important as models, if not more:

- Counter-models allow to *disprove implications*.
- Let P and Q be predicate formulas.
- Suppose that you want to prove that the predicate P implies Q is not valid.
- You can do so by choosing a domain, types for the variables, and interpretations which make P true and Q false.

A predicate formula with a counter-model

The following predicate formula is obtained from the one of two slides ago, swapping antecedent with consequent:

$$(\forall y. \exists x. P(x, y)) \text{ implies } (\exists x. \forall y. P(x, y))$$

The following is a counter-model for the formula above:

- Domain: the natural numbers.
- Type of the variables: natural numbers.
- Interpretation of $P(x, y)$: $x > y$.

In this counter-model, the formula means:

“if for every natural number there is a larger natural number,
then there is a natural number which is larger than every natural number”

which is clearly false.

A counter-model from Euclidean geometry

Consider the predicate formula:

$$\forall v, x, y, z. (T(v, x) \wedge T(v, y) \wedge T(v, z) \longrightarrow E(x, y) \vee E(x, z) \vee E(y, z))$$

A counter-model from Euclidean geometry

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We construct a counter-model as follows:

- As our domain, we choose Euclidean plane geometry.
- As types for variables, we make v be a straight line, and x, y, z be points.
- As interpretation for the predicates, we read $T(v, x)$ as “the straight line v goes *through* point x ”, and $E(x, y)$ as “points x and y are *equal*”.

A counter-model from Euclidean geometry

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Then the formula above is interpreted as:

“if a line of the Euclidean plane goes through three points,
then two of those three points coincide”

which is false.

...and a model too!

Consider again the predicate formula:

$$\forall v, x, y, z. (T(v, x) \wedge T(v, y) \wedge T(v, z) \longrightarrow E(x, y) \vee E(x, z) \vee E(y, z))$$

...and a model too!

Consider again the predicate formula:

$$\forall v, x, y, z. (T(v, x) \wedge T(v, y) \wedge T(v, z) \longrightarrow E(x, y) \vee E(x, z) \vee E(y, z))$$

We construct a model as follows:

- Domain: a *cube*.
- Variable types: v is an edge, and x, y, z are vertices.
- Interpretation: we read $T(v, x)$ as “the edge v has *terminal vertex* x ”, and $E(x, y)$ as “vertices x and y are *equal*”.

...and a model too!

Consider again the predicate formula:

$$\forall v, x, y, z. (T(v, x) \wedge T(v, y) \wedge T(v, z) \longrightarrow E(x, y) \vee E(x, z) \vee E(y, z))$$

We construct a model as follows:

- Domain: a *cube*.
- Variable types: v is an edge, and x, y, z are vertices.
- Interpretation: we read $T(v, x)$ as “the edge v has *terminal vertex* x ”, and $E(x, y)$ as “vertices x and y are *equal*”.

Then the formula above is interpreted as:

“if an edge of a cube has three terminal vertices,
then two of those three terminal vertices coincide”

which is true.