# Transfinite Semantics in the form of Greatest Fixpoint

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#### **Transfinite semantics**

Transfinite semantics: program execution can continue after completing an infinite subcomputation.

- Studied during the last decade.
- Can entail:
  - \* transfinite traces of execution steps in the case of iteration;
  - \* fractal traces of execution steps in the case of recursion.
- Useful in formalizing program slicing to avoid semantic anomaly.

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## Program slicing: example

Criterion:  $\{(7, sum)\}$ .

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## Semantic anomaly: example

If the original program loops then we might have slices which assign to interesting variables more times than the original program:

Criterion:  $\{(2, x)\}$ .

# **Greatest Fixpoint**

# Goal: greatest fixpoint form

We represent transfinite semantics in the form of greatest fixpoint of a monotone operator on complete lattices.

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## **Subgoals**

- Express transfinite semantics in a standard framework.
  - Express both transfinite and standard semantics in a uniform algebraic way.
- Provide an exhaustive definition of infinitely deep recursion semantics.
- As a plan for future: build a Cousot's hierarchy.

# **Epiphenomenons**

- Usual traces must be replaced by either fractional traces or trees.
- Explicit determinism is lost.

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#### **Fractional traces**

In the case of fractional traces, computation steps are indexed by rational numbers from a fixed interval.

- The interval of rationals within which an execution of a statement of the program falls does not depend on the initial state.
- Traces grow into depth rather than into length.

## **Example: swap**

The fractional trace of the execution of program

$$z := x; (x := y; y := z)$$

at initial state

$$\left\{
 \begin{array}{l}
 x \mapsto 1 \\
 y \mapsto 2 \\
 z \mapsto 0
 \end{array}
\right\}$$

is

$$\begin{array}{c|c}
0 & \frac{1}{2} & \frac{3}{4} & 1 \\
\hline \left\{\begin{matrix} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 0 \end{matrix}\right\} & \left\{\begin{matrix} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 1 \end{matrix}\right\} & \left\{\begin{matrix} x \mapsto 2 \\ y \mapsto 2 \\ z \mapsto 1 \end{matrix}\right\} & \left\{\begin{matrix} x \mapsto 2 \\ y \mapsto 1 \\ z \mapsto 1 \end{matrix}\right\}
\end{array}$$

## **Example: infinite loops**

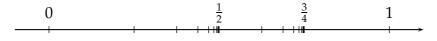
If

$$S_1 = S_2 =$$
while true do skip  $S_3 = x := 1$ 

then the domain of the execution trace of statement

$$S_1$$
;  $(S_2; S_3)$ 

is depicted in the following figure:



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# **Tree semantics**

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## **Trees**

In tree semantics, an execution is depicted in the form of tree.

 The tree structure reflects the proof of that execution within a deduction system.

## **Example: swap**

Here is the tree of the execution of the swap program

$$z := x; (x := y; y := z)$$

at the same initial state as before:

$$\frac{\left\{ \begin{array}{c} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 1 \\ z \mapsto 1 \end{array} \right\} }{\left\{ \begin{array}{c} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 1 \end{array} \right\}}$$

$$\frac{\left\{ \begin{array}{c} x \mapsto 1 \\ y \mapsto 2 \\ z \mapsto 0 \end{array} \right\} \rightarrow \left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 1 \\ z \mapsto 1 \end{array} \right\}}{\left\{ \begin{array}{c} x \mapsto 2 \\ y \mapsto 1 \\ z \mapsto 1 \end{array} \right\}}$$

# **Example generalized**

For any program of form  $S_1$  ;  $(S_2 \ ; S_3)$ , the tree grows as follows:

$$\begin{array}{ccc}
\vdots & \vdots \\
s_{\frac{1}{2}} \rightarrow s_{\frac{3}{4}} & s_{\frac{3}{4}} \rightarrow s_{1} \\
\hline
s_{0} \rightarrow s_{\frac{1}{2}} & s_{\frac{1}{2}} \rightarrow s_{1} \\
\hline
s_{0} \rightarrow s_{1} & s_{0} \rightarrow s_{1}
\end{array}$$

# The framework and results

#### Language

• Statements:

• Modules:

```
Module \rightarrow \texttt{proc} \ Proc \, (\ Var, \ \dots, \ Var) \ \texttt{is} \ Stmt \ | \ Module \; ; \; Module
```

## **Kinds of semantics**

We have considered the following kinds:

	Finite	Standard	Transfinite
Integral trace	<b>→</b>	$\overrightarrow{\omega}$	$\overrightarrow{\propto}$
Fractional trace	~	$\widetilde{\omega}$	$\widetilde{\propto}$
Tree	+	$\widehat{\omega}$	$\widehat{\propto}$

#### **Domains**

Val the set of values

State =  $Var \rightarrow Val$ 

 $\mathsf{Dom}_{\kappa}$  the set of individual semantic objects (traces, trees etc.)

$$Env_{\kappa} = \textit{Proc} \rightarrow (State \rightarrow Val^*) \rightarrow \wp(Dom_{\kappa})$$

The semantic domains  $\wp(\mathsf{Dom}_\kappa)$  are equipped with inclusion order, lifted componentwise to functions.

#### **Signatures**

• Statement level.

$$\mathcal{F}_{\kappa} \in \operatorname{Env}_{\kappa} \to (Stmt \to \wp(\operatorname{Dom}_{\kappa})) \to (Stmt \to \wp(\operatorname{Dom}_{\kappa}))$$
 $\mathcal{S}_{\kappa} \in \operatorname{Env}_{\kappa} \to (Stmt \to \wp(\operatorname{Dom}_{\kappa}))$ 
 $\mathcal{S}_{\kappa}(S)(e) = \operatorname{gfp}(\mathcal{F}_{\kappa}(e))(S)$ 

• Module level.

$$\mathcal{G}_{\kappa} \in (Module \to \operatorname{Env}_{\kappa}) \to (Module \to \operatorname{Env}_{\kappa})$$

$$\tau_{\kappa} \in Module \to \operatorname{Env}_{\kappa}$$

$$\tau_{k}(M) = \operatorname{gfp}(\mathcal{G}_{k})(M)$$

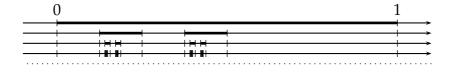
#### **Correctness**

- The functions  $\mathcal{F}_{\kappa}(e)$  and  $\mathcal{G}_{\kappa}$  are monotone.
  - By Tarski's theorem, the greatest fixpoint always exists and the definition is correct.
- The functions  $\mathcal{F}_{\kappa}(e)$  and  $\mathcal{G}_{\kappa}$  are Scott-cocontinuous for  $\kappa = \widetilde{\alpha}$ ,  $\kappa = \widehat{\alpha}$ .
  - \* By Kleene's theorem, the greatest fixpoint of the transfinite semantics can be obtained by an iteration which is not transfinite!

# Example

Let procedure q be defined by

The iteration of its semantics goes as follows:



# Remarks

#### The choice of the kind of semantics

Why do we need the fractional traces or trees? Why couldn't we use transfinite sequences?

- It is not possible to express fractal structures that arise in the case of infinitely deep recursion using transfinite sequences.
- Even in the case of infinite iteration only, the greatest fixpoint of our function would contain too many traces.
  - Besides the desired traces, all traces having a desired trace as a prefix would be included.
  - But in fractional semantics, the interval [0;1] is wholly distributed between all statements occurring in the program and no space is left for garbage.

#### **Connection between different kind of semantics**

Fractional traces reflect the deduction tree structure within a linear order. They have both trace and tree properties.

This way, fractional semantics is an intermediate level between trace and tree semantics.

#### **Non-determinism**

The price we pay in this approach is that explicit determinism is lost.

- It is not clear whether the execution trace of a program at an initial state is unique.
- It is not clear whether there exists an execution trace after all!
  - \* What would the absence of execution traces mean?

Under some natural restrictions, it can be proven that non-determinism can be introduced by infinitely deep recursion only.