

# Automatic code generation in certified system development: a model driven specification and verification approach

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## Plan

### 1 Introduction

### 2 Simulink/Scicos block library

### 3 Block level verification

### 4 System level verification

### 5 Conclusion

## Application Context

### ● Context

- Critical embedded system development
  - Certification (DO-178, ECSS, ISO-26262, IEC-61508)
- Automatic code generation
  - Tools must be qualified according to DO-330 (adapted from DO-178C)
  - Formal methods use allowed by DO-333 (supplement to DO-178C)
  - Model-based techniques use allowed by DO-331 (supplement to DO-178C)

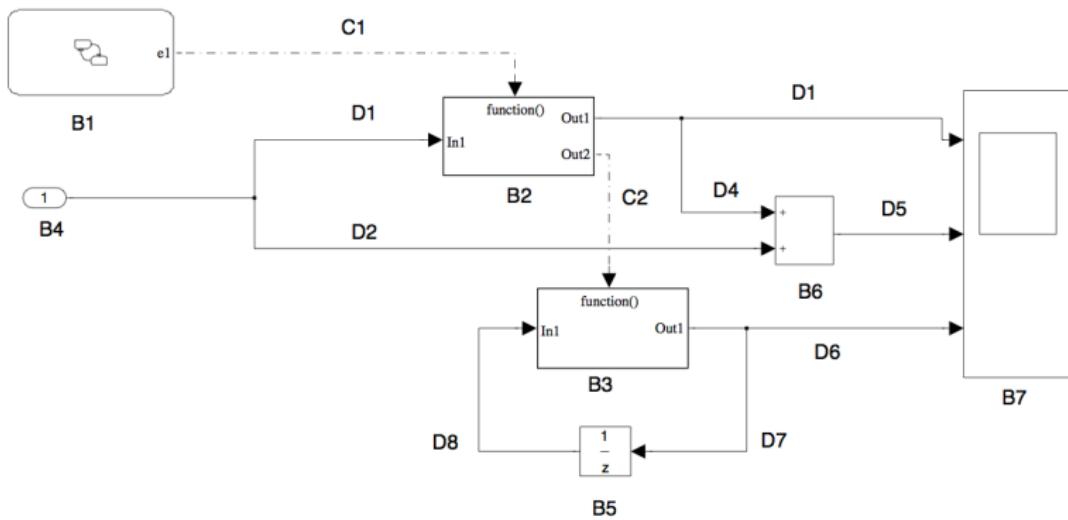
### ● Purpose

- Verification of the functional correctness of the generated code according to the specification
- Reduce source code verification testing
- Reduce the risk of anomalies in source code



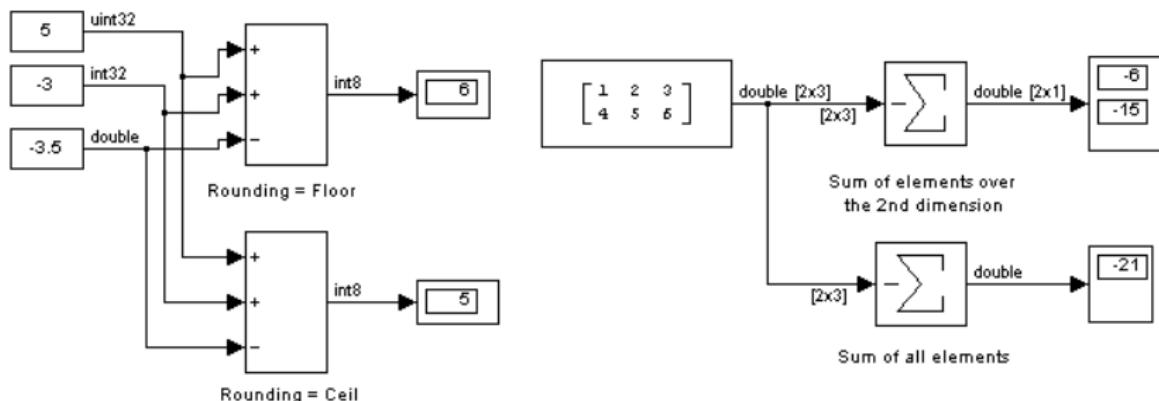
## Simulink-Stateflow/Scicos

- Discrete control and command algorithm specification
  - Blocks : Elementary (language operation), Hierarchical, User functions
  - Signals between Block Ports (data flow/event based control flow)



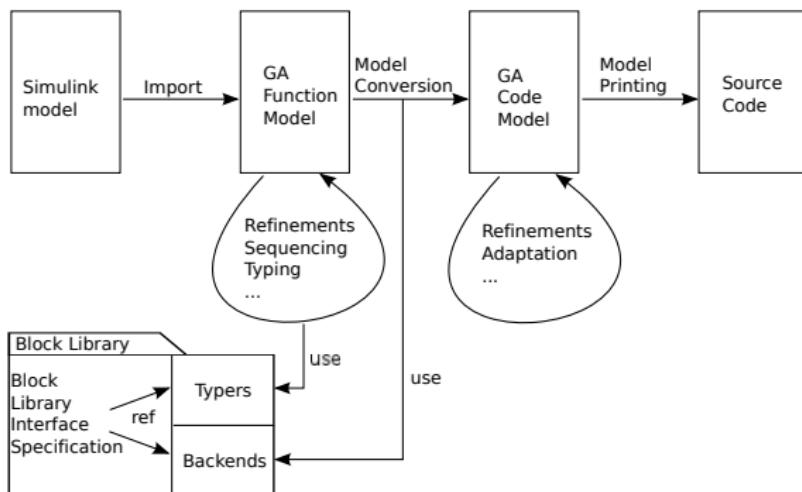
## The Sum block specification

- Simulink version of the **Sum** block has quite a lot of variability : sum of inputs, sum of elements, sum of dimension, saturation, rounding, scalar expansion, etc
- Original documentation : 19 pages on the meaning of parameters
- Contains many ambiguities and errors



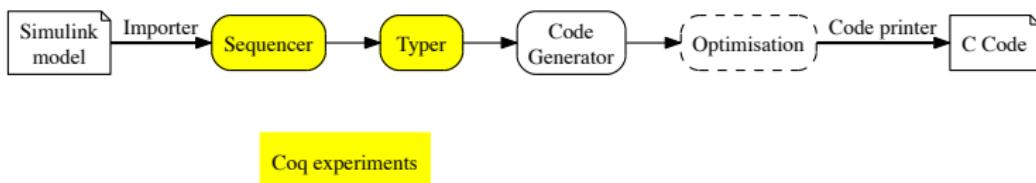
## GeneAuto

- Open source embedded code generator developed in project GeneAuto. Extended in projects P and Hi-MoCo.
- Takes Simulink-Stateflow/Scicos models as input
- Outputs C, Ada or Java code



## GeneAuto

- Verification process combining formal (proof assistant) and classic approaches (test, proofreading)
- Some of the elementary tools were developed using the proof assistant Coq



## Needs to be addressed

- Formal specification of the semantics of the code generator input languages
  - Suited for use by industrial system and software engineers
- Verification (preferably automatic)
  - Soundness and completeness of each elementary block specification
  - Providing artifacts for the generated code verification
- Generated code verification
  - Conformance of elementary blocks specification and implementation

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## Block library specification<sup>1</sup>

- Contains specifications of blocks that are supported by the given code generator configuration
- Block specification consists of
  - Number and type of input and output ports
  - Required state variables and their types
  - Parameters and their types
  - Allowed type combinations
  - Semantics of the block
- Complexity lies in each block semantics and the combination of inputs/outputs/parameters/state variables types and their multiplicities
- Leads to sophisticated variability and complex specification



## Mathematical representation

- Pros

- Easily to read, understand and write by engineers

- Cons

- General purpose language
- Too much freedom in specification writing
- Hard to maintain
- No dedicated variability management

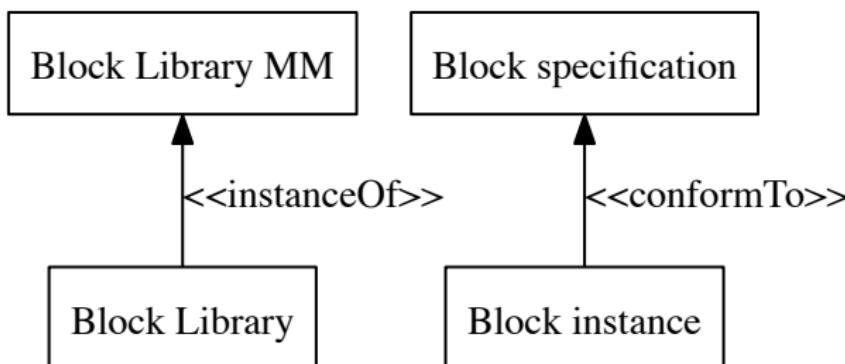
$\mathcal{P}(\text{Inputs})$  The  $\mathcal{P}(\text{Inputs})$  parameter is defined as the following :  
–  $\forall i \in [1, n_{in}], \exists op_i \in [+,-], \mathcal{P}(\text{Inputs}) = \{op_i\}$

Input must be one of the following :

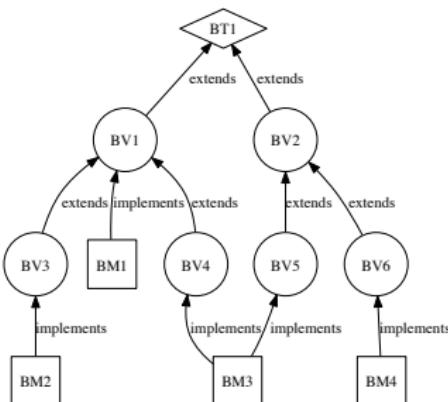
1.  $\mathcal{I} = \{\forall i \in [1, n_{in}], X_i \in \mathbb{T}\}$
2.  $\mathcal{I} = \{n_{in} = 1, X \in \mathcal{V}_n(\mathbb{T}_{\setminus \mathbb{B}})\}$
3.  $\mathcal{I} = \left\{ n_{in} > 1, \left\{ \begin{array}{l} X_i \in \mathcal{V}_n(\mathbb{T}_{\setminus \mathbb{B}}) \\ X_i \in \mathbb{T}_{\setminus \mathbb{B}} \Rightarrow X_i \leftarrow \mathcal{V}_n(\mathbb{T}_{\setminus \mathbb{B}}) \wedge a_1 = \dots = a_n \end{array} \right\} \right\}$
4.  $\mathcal{I} = \left\{ n_{in} > 1, \left\{ \begin{array}{l} X_i \in \mathcal{M}_{n,m}(\mathbb{T}_{\setminus \mathbb{B}}) \\ X_i \in \mathbb{T}_{\setminus \mathbb{B}} \Rightarrow X_i \leftarrow \mathcal{M}_{n,m}(\mathbb{T}_{\setminus \mathbb{B}}) \wedge a_{1,1} = \dots = a_{n,m} \end{array} \right\} \right\}$

## We found a solution

- General purpose language → use DSLs
- Too much freedom in specification writing → use DSLs
- Hard to maintain → DSLs ease maintenance
- No dedicated variability management → A DSL with variability management

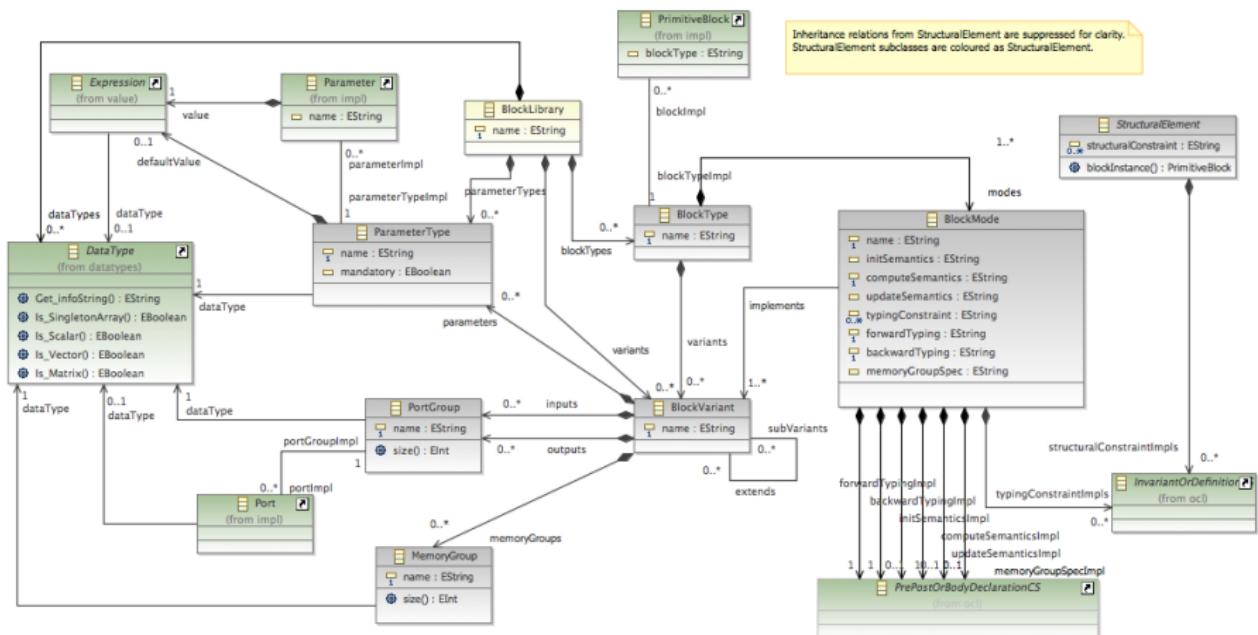


## DSL-based specification



- MOF/Ecore-based formalism : well accepted in the industry and **standardized**
  - **Variant** : set of related parameters and associated block ports
  - **Mode** : valid configuration (set of block variants)
  - **Structural correctness** as OCL invariants on modes and variants
  - **Typing/Computational semantics** as OCL pre/post conditions on modes

# DSL-based specification - Meta-Model



## Textual specification : Types, Variants

```
library GeneAuto {
    type bool = enum {'true', 'false'};
    type signsChar = enum {'+', '-', '|'};
    type stringSigns = signsChar[1,256];
    block Sum {
        variant Default {
            parameter Signs : stringSigns ;
            parameter IntegerRoundingMode : enum {'Ceiling', 'Convergent',
                'Floor', 'Nearest', 'Round', 'Simplest', 'Zero'
            } ;
            parameter SaturateOnIntegerOverflow : bool ;
        }
        variant SingleInput extends Default {
            in in0;
            out out0;
            invariant signsSize : Signs.size() = 1
            invariant signsValue : Signs = "+" or Signs = "-"
        }
        variant MultipleInputs extends Default {
            in inGroup[2,-1];
            out out0;
            parameter SumOver : enum {'AllDimensions', 'SpecifiedDimension'};
            parameter Dimension : int;
            invariant signsSize : Signs.size() = inGroup->size()
            invariant signsValue :
                Signs.split("|")->forAll(stl
                    st.lsplit("+")->forAll(st1
                        st1.lsplit("-")->forAll(st2|st2.size()=0)
                    )
                )
            invariant dimensionValue : Dimension = 1 or Dimension = 2
        }
    }
}
```



## Textual specification : Modes, Semantics

```
mode SumOfAllElements implements SingleInput {
    invariant SumOverValue : SumOver = 'AllDimensions'
    specification compute output_computation :
        if (in0.isScalar) then
            if (Signs = "+") then
                out0 = in0
            else
                out0 = 0 - in0
        else
            if (in0.isVector) then
                if (Signs = "+") then
                    out0 = in0->sum()
                else
                    out0 = 0 - in0->sum()
            else
                if (in0.isMatrix) then
                    if (Signs = "+") then
                        out0 = in0->collect(in0_elem | in0_elem->sum())->sum()
                    else
                        out0 = in0->collect(in0_elem | 0 - in0_elem->sum())->sum()
```



## Associated tools

- Textual editor :
  - Auto-completion
  - Static semantics check
- Documentation generation :
  - Mathematical view of the specification
  - Graphical representation of the variants/modes hierarchy
  - Adaptable/easy to maintain

### 2 Sum

#### 2.1 Parameters

Parameter name	Possible values or DataType
Signed	string
IntegerRoundingMode	['Ceiling', 'Convergent', 'Floor', 'Nearest', 'Round', 'Simplest', 'Zero']
SaturateOnIntegerOverflow	bool
SumOver	['AllDimensions', 'SpecifiedDimension']
Dimension	int

#### 2.2 Modes hierarchy



#### 2.3 Modes

##### 2.3.1 Mode SumOfAllElements

- Variant hierarchy



- Input Ports

Port name	Port rank	Port multiplicity	Port data type
inf	0	0	null

- Output Ports

## Future applications

- Verification of the soundness/completeness of the block specification (variability aspect)
  - OCL constraints on the BlockLibrary metamodel (structural correctness)
  - Generation of inductive data types for verification in a proof assistant
  - Embedded OCL constraints in block specification (dynamic semantics)
    - Generate predicates for dependent types
    - High level properties check in other kinds of proof environments
- Generation of typing and code generation functions from the formal block specification
- Generation of test cases
- Conformance checking between block instance and block library specification

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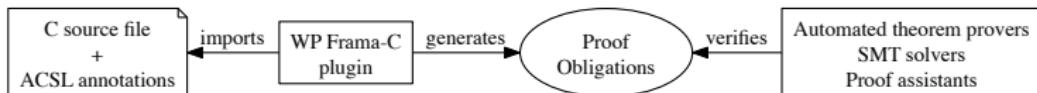
Model Compilers  
for Safety-Critical Systems

## Questions to answer

- How to verify an automated code generation ?
- How to handle the industrial constraints ?
- How to reduce the costs of the use of formal verification for common engineers ?

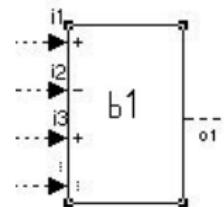
## Static analysis

- Static analysis based verification (deductive kind)
- Subset of C compatible with CompCert-C<sup>2</sup>
- Hoare triples using ACSL<sup>3</sup>
  - Pre/Post conditions
  - Variants and Invariants (loops)
  - Annotations for the data flows between blocks
- Frama-C : Weakest preconditions calculus combined with automated SMT solvers (boolean Satisfaction Modulo Theories)



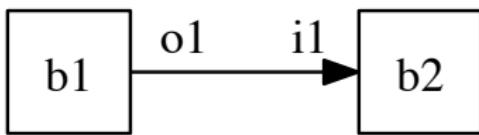
## Generation of an annotated code for a block

```
1  /*@ requires \forall integer m; 0 <= m < vector_size ==>
2      \valid(&b1.o1+m) && ... ;
3  ensures \forall integer m; 0 <= m < vector_size ==>
4      b1.o1[m] == b1.i1[m] - b1.i2[m] + ... ; */
5 {
6     /*@ loop invariant 0 <= index <= vector_size;
7         loop invariant \forall integer m; 0 <= m < index ==>
8             b1.o1[m] == b1.i1[m] - b1.i2[m] + ... ;
9         loop variant vector_size - index;
10    */
11    for (int index = 0; index < vector_size; index++){
12        b1.o1[index] = b1.i1[index] - b1.i2[index] + ...;
13    }
14 }
```



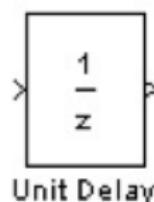
## Annotations for the data flows between blocks

```
1  /*@ ensures \forall integer n; 0 <= n < vector_size ==>
2      b2.i1[n] == b1.o1[n];
3  */
4  {
5      /*@ loop invariant 0 <= index <= vector_size;
6          loop invariant \forall integer n; 0 <= n < index ==>
7              b2.i1[n] == b1.o1[n];
8          loop variant 2-index;
9      */
10     for(index=0; index < vector_size; ++index){
11         b2.i1[index] = b1.o1[index];
12     }
13 }
```



## Annotations for a block initialization 1/2

```
1  typedef struct{
2      double d_in[2];
3      double d_out[2];
4  }t_struct;
5
6  typedef struct{
7      double d_mem[2];
8  }t_struct_memory;
9
10 t_struct b;
11 t_struct_memory mem;
12
13 /*@ requires \valid(&mem.d_mem+(0..1));
14     ensures \forall integer n; 0 <= n < 2 ==> mem.d_mem[n] == 0.0;
15 */
16 void init(){
17     /*@ loop invariant 0 <= i <= 2;
18     loop invariant init_memInvariant:
19         \forall integer n; 0 <= n < i ==> mem.d_mem[n] == 0.0;
20     loop variant 2-i;
21 */
22     for (int i=0;i<2;i++){
23         mem.d_mem[i] = 0.0;
24     }
25 }
```

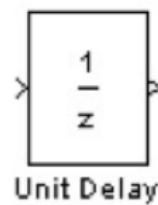


Unit Delay



## Annotations for a block initialization 2/2

```
1 //@ ghost double pre_mem[2];
2
3 /*@ requires \valid(&b.d_in+(0..1)) && \valid(&b.d_out+(0..1)) &&
4     \valid(&mem.d_mem+(0..1));
5     ensures \forall integer n; 0 <= n < 2 ==>
6         b.d_out[n] == pre_mem[n] &&
7         mem.d_mem[n] == b.d_in[n];
8 */
9 void compute(){
10    /*@ loop invariant 0 <= i <= 2;
11       loop invariant get_memInvariant: \forall integer n; 0 <= n < i ==>
12           b.d_out[n] == pre_mem[n];
13       loop invariant set_memInvariant: \forall integer n; 0 <= n < i ==>
14           mem.d_mem[n] == b.d_in[n];
15       loop variant 2-i;
16   */
17   for (int i=0;i<2;i++){
18     b.d_out[i] = mem.d_mem[i];
19     //@ ghost pre_mem[i] = mem.d_mem[i];
20     mem.d_mem[i] = b.d_in[i];
21   }
22 }
```



## Using Frama-C

- WP/Jessie : proof obligations generation
- SMT solvers : assess the satisfaction of the proof obligations

Information	Messages	Console	Properties	WP Proof Obligations							
Module	Function	Behavior	Origin		Model	Kind	Alt-Ergo	Coq	Z3	Simplify	
sum_vector.c	f		loop invariant $(0 \leq i) \wedge (i \leq 2)$ ;		store	Establishment	✓	✓	✓	✓	
sum_vector.c	f		loop invariant $(0 \leq i) \wedge (i \leq 2)$ ;		store	Preservation	✓				
sum_vector.c	f		loop invariant $\forall \mathbb{Z} m; (i < m) \wedge (m < 2) \Rightarrow (\text{vect.Sum}[m] \equiv \text{vect.Sum}[m], \text{Pre})$ ;		store	Establishment	✓				
sum_vector.c	f		loop invariant $\forall \mathbb{Z} m; (i < m) \wedge (m < 2) \Rightarrow (\text{vect.Sum}[m] \equiv \text{vect.Sum}[m], \text{Pre})$ ;		store	Preservation	✓				
sum_vector.c	f		loop invariant $\forall \mathbb{Z} m; (0 \leq m) \wedge (m < i) \Rightarrow (\text{vect.Sum}[m] \equiv \text{vect.Sum}[m] + \text{vect.Const1}[m])$ ;		store	Establishment				✓	
sum_vector.c	f		loop invariant $\forall \mathbb{Z} m; (0 \leq m) \wedge (m < i) \Rightarrow (\text{vect.Sum}[m] \equiv \text{vect.Sum}[m] + \text{vect.Const1}[m])$ ;		store	Preservation			✓		
sum_vector.c	f		loop variant $2 \cdot i$ ;		store	Decreasing	✓				
sum_vector.c	f		loop variant $2 \cdot i$ ;		store	Positive	✓				
sum_vector.c	f		ensures $\forall \mathbb{Z} m; (0 \leq m) \wedge (m < 2) \Rightarrow (\text{vect.Sum}[m] \equiv \text{vect.Sum}[m] + \text{vect.Const1}[m])$		store	Proof Obligation			✓		



## Main issues

- Partially automatic generation of loops variants and invariants
  - Affordable complexity
  - Verification efficiency
- Introducing invariants in the generation
  - Synthesized by the tools (based on code patterns, pre/post-conditions)
  - Provided by the code generator developers

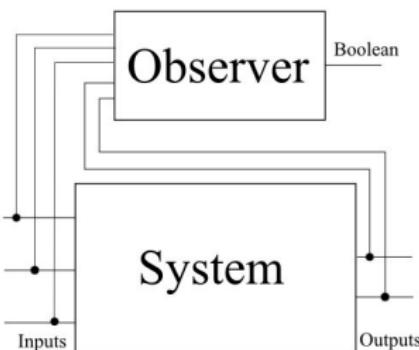
- Work done<sup>4</sup>
  - Extension of GeneAuto in order to handle annotation generation
    - Annotation model for generic annotation expressions
    - Extension of the CPrinter tool for annotation printing
- Work to do
  - Experiment about scaling
  - Extraction of loop invariants from block specification
- Expected result
  - Automated verification of the generated code according to the expected behavior (pre/post conditions for the blocks)

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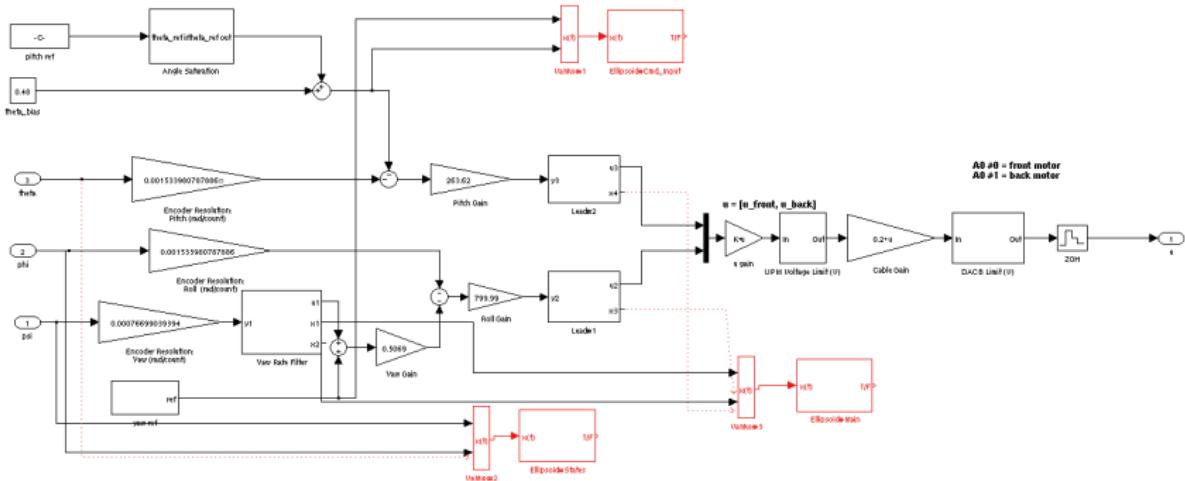
## The observer approach

- Expressing the system expected behavior using system design language (system engineer level)
  - Related to execution context, model of the external world, simulations
- Observer  $\Rightarrow$  Behavioral property of the whole system
- Verify the generated verification conditions with Frama-C



## Specific annotation blocks

- Specific blocks have been implemented for experimentation with GeneAuto
  - VAMux
    - Create ghost annotations for system data usage in annotations (bridge between system generated code and annotations)
  - Ellipsoid
    - Stability invariant used in control theory (Lyapunov function)



## On going work

- Verification-container block to be implemented
  - Holds a sub-system used only for verification (annotation generation)
  - This sub-system is made of elementary Simulink/Scicos blocks
  - Generalisation of the observer block directly specified using domain blocks
- Extension of the block library specification method to handle specification of annotation blocks

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## Conclusion

- Block Library specification
  - DSL for formal specification of a block library
  - Complexity of the blocks managed using a feature modeling approach
  - OCL constraints expressions for semantics specification
- Applications
  - Textual editor / Documentation generation
  - Verification of the generated code semantics
    - Pre/Post conditions for the whole system
    - Pre/Post conditions for each block
    - Invariants for blocks and data flows

## Future work

- Code generation
  - Invariants/Variants, Pre/Post conditions generation
    - According to code patterns
    - From specification
  - Integration in the development and qualification processes
- Block Library specification
  - Soundness/Correctness verification
  - Generation of
    - Code generator components (backends, typers)
    - Test cases

Thanks for your attention

BlockLibrary : <http://dieumegard.perso.enseeiht.fr/blocklibrary>  
GeneAuto : <http://www.geneauto.org>  
ProjectP : <http://www.open-do.org/projects/p>